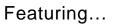


Hydraulic and Electrohydraulic Actuators

Series 2HX



- Two Valve Manifold Options
 - 7 Standard Bolt-on Manifolds
 - 4 Standard Integral Manifolds
- Two Feedback Options
 - LDT – LRT



145

Parker Series 2HX Actuators..

Bolt-on and Integral Servo/ Proportional/NFPA Valve Manifolds and Two Feedback Options

Series 2HX Electrohydraulic Actuators are specifically designed to meet today's demand for more efficient, low cost actuators that meet your application requirements.

To ensure that every electrohydraulic actuator is premium quality, we subject each and every one – not just batch samples – to tough inspection **and** performance tests. Plus as the world's largest and lowest cost cylinder producer, we offer you the Series 2HX electrohydraulic actuator at the lowest cost that helps you stretch those tight design budgets without sacrificing quality.

Worldwide Distribution

The Parker System is a worldwide network of manufacturing plants and distribution centers for fast, dependable service and delivery. Parker provides you with local sales and technical assistance from hundreds of stocking distributors and regional offices.

Contact Parker Cylinder Division for further assistance or information on designing the Series 2HX electrohydraulic actuator to meet your motion control requirements.

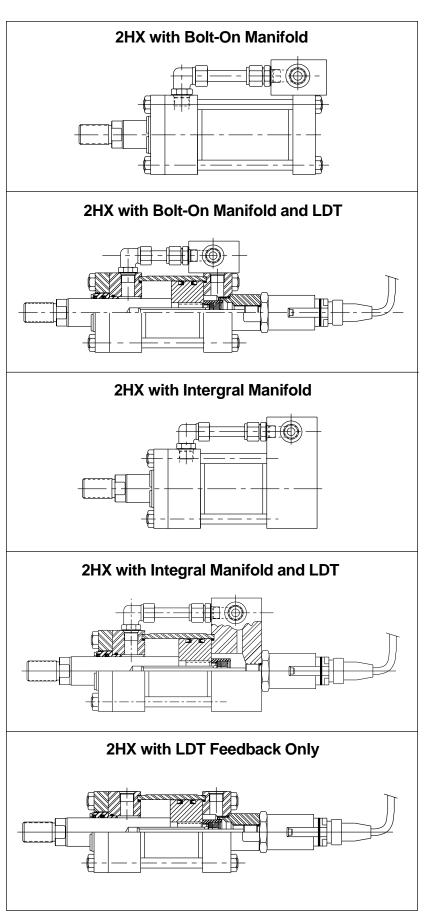


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Note: for application information relating to the selection of cylinders

based on bore sizes, rod diameters and mounting styles, refer to your current Parker Hydraulic Cylinder Catalog 0106, Section C or consult your Parker distributor.

Table A – Available Mounting and Manifold Position

	DESCRIPTION	MOUNTIN	MANIFOLD G POSITION	INTEGRAL MANIFOLD	APPLICABLE FEEDBACK DEVICES
UTTLE		CAP END ¹	HEAD END ¹	CAP END ONLY	T LEBBAOK DE TIOLO
TB	Head Tie Rods Extended	1,2,3,4	1,2,3,4	1	
TC	Cap Tie Rods Extended	1,2,3,4	1,2,3,4	N/A	LRT and LDT†
TD	Both Ends Tie Rods Extended	1,2,3,4	1,2,3,4	N/A	
J	Head Rectangular Flange	1,2,3,4	CF	1	
JB	Head Square Flange	1,2,3,4	CF	1	LRT and LDT
JJ	Head Rectangular	1,2,3,4	CF	1	
Н	Cap Rectangular Flange	CF	1,2,3,4	N/A	LDT
HB	Cap Square Flange	CF	1,2,3,4	N/A	LRT
HH	Cap Rectangular	CF	1,2,3,4	N/A	LRT and LDT†
С	Side Lug	1	1	1	
E	Centerline Lug	1,3	1,3	N/A	LRT and LDT
F	Side Tapped	1;2&4 CF	1;2&4 CF	1	
CB	Side End Angles	1;2&4 CF	1;2&4 CF	N/A	LDT
G	Side End Lugs	1;2&4 CF	1;2&4 CF	N/A	LRT
BB*	Cap Fixed Clevis	CF	1,2,3,4	1	LRT and LDT ⁺⁺
D	Head Trunnion	1,2,3,4	1,3	1	
DB	Cap Trunnion			N/A	LRT and LDT
DD	Intermediate Fixed Trunnion	1,2,3,4	1,2,3,4	1	
SB*	Spherical Bearing	CF	1,2,3,4	1	LRT and LDT ⁺⁺

Note:

Overhang of Bolt-On-Manifold may affect mounting and application of cylinder, consult factory.

If cylinder has cushions, needle and check valve will be located at standard positions. 1

† LDT Feedback devices extend beyond the face of the cap and may interfere with cap end mounts - consult LDT dimensions in this catalog.

++ When LDT Feedback devices are selected with cap end mounts a false stage cylinder body is required. See dimensions and information on page 176.

For Cylinder Division Plant Locations - See Page II.



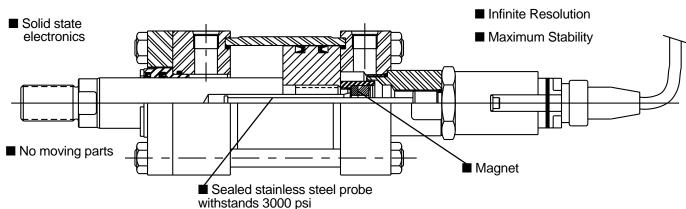
N/A = Not Available

CF = Consult Factory

Compact design for

easy installation

Linear Displacement Transducer Series 2HX-LDT



Magnetostriction

In a LDT position sensor, a pulse is induced in a speciallydesigned magnetostrictive waveguide by the momentary interaction of two magnetic fields. One field comes from a movable magnet which passes along the outside of the sensor tube, the other field comes from a current pulse or interrogation pulse launched along the waveguide. The interaction between the two magnetic fields produces a strain pulse, which travels at sonic speed along the waveguide until the pulse is detected at the head of the sensor. The position of the magnet is determined with high precision by measuring the elapsed time between the launching of the electronic interrogation pulse and the arrival of the strain pulse. As a result, accurate noncontact position sensing is achieved with absolutely no wear to the sensing components.

PULSES	ПП	Π	П
	l ⊲ −td−►l	٨	Λ
PULSES _ RECEIVED	<u>}</u>		DLTAGE
PULSE TRAIN - AVERAGE DC OUTPUT 0-	DC		

An average of 200 ultrasonic strain pulses are launched for every reading. With so many readings taken for each position, vibration and shock have negligible effect on the readings. The transducer assembly is shielded to eliminate interference caused by electromagnetic fields in the radio frequency range. In addition, static magnetic fields of several hundred gauss must get as close as 3/16" from the protective tube before any interference in transducer operation occurs.

Standard Specifications

Parameter	Specification
Resolution:	Analog: Infinite Digital: 1 ÷ [gradient x crystal freq. (mHz) x circulation]
Non-Linearity:	±0.02% or ±0.05 mm (±0.002 in.), whichever is greater 0.002 in. is the minimum absolute linearity and varies with sensor model
Repeatability:	Equal to resolution
Hysteresis:	<0.02 mm (0.0008 in.)
Outputs:	Analog: Voltage or Current Digital: Start/Stop or PWM
Measuring Range:	<i>Analog:</i> 25 to 2000 mm (1 to 78 in.) <i>Digital:</i> 25 to 7600 mm (1 to 300 in.)
Operating Voltage:	+13.5 to 26.4 Vdc (±0%): Strokes ≤1525 mm (60 in.) +24 Vdc (±10%): Strokes > 1525 mm (60 in.)
Power Consumption:	100 mA
Operating Temperature:	Head Electronics: -40 to 70°C (-40 to 158°F) Sensing Element: -40 to 105°C (-40 to 221°F)
EMC Test*:	DIN EN 50081-1 (Emissions); DIN EN 50082-2 (Immunity)
Shock Rating:	100 g (single hit)/IEC standard 68-2-27 (survivability)
Vibration Rating:	5 g/10-150 Hz/IEC standard 68-2-6
Adjustability: (for active sensors only)	Field adjustable zero and span to 5% of active stroke
Update Time:	Analog: ≤1 ms Digital: Minimum = [Stroke (specified in inches) + 3] x 9.1 µs
Operating Pressure:	5000 psi static; 10,000 psi spike
Housing Style/ Enclosure:	Aluminum die-cast head, IP 67 stainless steel rod & flange (LH flange: M18 x 1.5 or 3/4-16 UNF-3A)

*EMC test specification does not include sensors with the RB connection style. The above specifications for analog sensors are assuming that output ripple is averaged by the measuring device as with any typical analog device. Specifications are subject to change without notice. Consult the factory for specifications critical to your needs.

Cylinder with Linear Displacement Transducer

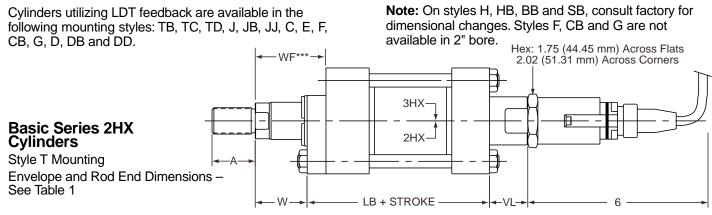


Table 1 – Envelope and Rod End Dimensions

For additional dimensions, consult Series 2H and Series 3H 7" and 8" Bore, of this catalog.

Bore	Rod No.	Rod Dia. mm	А	KK Style 4	CC Style 8	LB Add Stroke	VL	4 to 1 Design Factor (PSI)**
0	1	1			-			
2	2	1 ³ /8	1 ⁵ /8	1-14	1 ¹ /4 - 12	5.25	1 ³ /8	3000
	1	1						
2 ¹ / ₂	2	1 ³ /4	2	1 ¹ / ₄ - 12	1 ¹ /2 - 12	5 ³ /8	1 ³ /8	3000
	3	1 ³ /8	1 ⁵ /8	1-14	11/4 - 12	5 ³ /8	1 ³ /8	3000
	1	1 ³ /8	1 ⁵ /8	1-14	1 ¹ /4 - 12	6 ¹ / ₄	1 ¹ / ₄	2130
3 ¹ / ₄	2	2	2 ¹ /4	1 ¹ / ₂ - 12	1 ³ / ₄ - 12	6 ¹ / ₄	1 ¹ / ₄	3000
	3	1 ³ / ₄	2	1 ¹ / ₄ - 12	1 ¹ / ₂ - 12	6 ¹ / ₄	1 ¹ / ₄	3000
	1	1 ³ /4	2	1 ¹ / ₄ - 12	1 ¹ /2 - 12	65/8	1 ¹ / ₄	2580
4	2	2 ¹ / ₂	3	1 ⁷ /8 - 12	2 ¹ / ₄ - 12	65/8	1 ¹ / ₄	3000
	3	2	2 ¹ / ₄	1 ¹ / ₂ - 12	1 ³ /4 - 12	65/8	1 ¹ / ₄	3000
	1	2	2 ¹ /4	1 ¹ / ₂ - 12	1 ³ /4 - 12	7 ¹ / ₈	1 ¹ / ₄	2510
_	2	3 ¹ / ₂	3 ¹ / ₂	2 ¹ / ₂ - 12	3 ¹ /4 - 12	7 ¹ / ₈	1 ¹ / ₄	3000
5	3	2 ¹ / ₂	3	1 ⁷ /8 - 12	2 ¹ /4 - 12	7 ¹ /8	1 ¹ / ₄	3000
	4	3	3 ¹ / ₂	21/4 - 12	2 ³ / ₄ - 12	7 ¹ / ₈	1 ¹ / ₄	3000
	1	2 ¹ / ₂	3	1 ⁷ /8 - 12	2 ¹ / ₄ - 12	8 ³ /8	1 ³ /8	3000
0	2	4	4	3 - 12	3³/4 - 12	8 ³ /8	1 ³ /8	3000
6	3	3	3 ¹ / ₂	21/4 - 12	2 ³ / ₄ - 12	8 ³ /8	1 ³ /8	3000
	4	3 ¹ / ₂	3 ¹ / ₂	2 ¹ / ₂ - 12	31/4 - 12	8 ³ /8	1 ³ /8	3000
	1	3	3 ¹ / ₂	21/4 - 12	2 ³ /4 - 12	9 ¹ / ₂	¹³ / ₃₂	3000
	2	5	5	31/2 - 12	4 ³ / ₄ - 12	9 ¹ / ₂	¹³ / ₃₂	3000
7*	3	3 ¹ / ₂	3 ¹ / ₂	2 ¹ / ₂ - 12	31/4 - 12	9 ¹ / ₂	¹³ / ₃₂	3000
	4	4	4	3 - 12	3³/₄ - 12	9 ¹ / ₂	¹³ / ₃₂	3000
	5	4 ¹ / ₂	4 ¹ / ₂	31/4 - 12	4 ¹ / ₄ - 12	9 ¹ / ₂	¹³ / ₃₂	3000
	1	3 ¹ / ₂	3 ¹ / ₂	2 ¹ / ₂ - 12	3 ¹ /4 - 12	10 ¹ / ₂	¹³ / ₃₂	3000
	2	5 ¹ /2	5 ¹ /2	4 - 12	5 ¹ /4 - 12	10 ¹ / ₂	¹³ / ₃₂	3000
8*	3	4	4	3 - 12	3³/₄ - 12	10 ¹ / ₂	¹³ / ₃₂	3000
	4	4 ¹ / ₂	4 ¹ / ₂	31/4 - 12	4 ¹ / ₄ - 12	101/2	¹³ / ₃₂	3000
	5	5	5	3 ¹ / ₂ - 12	4 ³ / ₄ - 12	10 ¹ / ₂	¹³ / ₃₂	3000

†Note: The rod end dimensions shown are based on the use of a linear displacement transducer with a rod end dead zone of 2.5 inches or less. LDT's with longer dead zones require a rod extension. The LDT will be permanently damaged if the proper rod extension is not used. Consult factory if an LDT with longer dead band is going to be used.

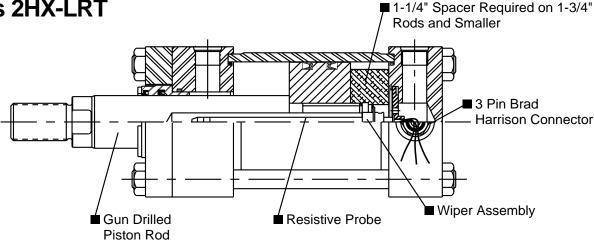
 $^{\ast\ast}\mbox{The 4:1}$ design factor is based on the tensile strength of the piston to rod connection.

*Specify Series 3HX.

***For 7-8" Bore 3HX callout dimension WF.



Linear Potentiometer Series 2HX-LRT



Standard Features

- Available in strokes to 120".
- Unique, easy to apply cylinder position sensing system.
- Infinite resolution, high linearity and repeatability.
- Innovative, resistive element is made of conductive plastic.
- 3 pin Brad Harrison electrical connector available at any cap position not occupied by a port or mount.

How It Works

The Parker LRT is a uniquely designed position sensor that uses a resistive element and wiper assembly to provide an analog output signal of a cylinder's position. The LRT is a dual element type linear potentiometer with two independent elements mounted on either side of a anodized aluminum extrusion. The LRT operates as a voltage divider. This is done by shorting through the extrusion with the wiper assembly. The position of the wiper changes the resistive load proportional to its position along the cylinder stroke. The LRT is energized by applying a voltage across the unit, typically 10 VDC. As the resistive load changes with the cylinder stroke, the output voltage changes proportionally. The output voltage at the end point of the cylinder stroke is dictated by the input voltage applied across the device. The probe is mounted into the cylinder cap and inserted into the gun drilled piston rod. The compactness of the design only adds to the envelope dimensions of cylinders with 1-3/4" rods and smaller. Envelope dimensions of cylinders with larger rods are unaffected.



Standard Specifications

- Non-Linearity Less than 0.1% of full scale up to 48" stroke. Less than 1.0% of full scale over 48" stroke.
- Repeatability .001 inch
- Input Voltage Nominal 5-50 Vdc
- Operating Temperature Range -40°F to +160°F
- Cylinder Stroke Length Up to 120"
- Electrical Connector Brad Harrison 3-pin micro connector interface at pos. #4 standard. (Unless occupied by a port or mount.)
- Total Resistance 800 per inch of stroke (\pm 20%) + end resistance.
- End Resistance 800
- Maximum Velocity 30 inches per second
- Life Expectancy Greater that 50 x 10⁶ cycles (Based on 1" stroke @ 10 ips)
- Fluid Medium Petroleum based hydraulic fluids
- End Voltage Loss (V source) x 400/stroke x 800)
- Power Dissipation supply voltage squared, divided by the total resistance.

The LRT requires a high impedance interface greater than 100K ohms. A maximum of 1 microamp should be required from the LRT.

Pin Chart

Pin Number	On Cable	On LRT	Function
1	Green	White (wiper)	Output
2	Red w/Blk	Black (resistor base)	V-
3	Red w/White	Red (resistor tip. power)	V+

Cylinder with Linear Potentiometer Feedback (LRT)

Cylinders utilizing LRT feedback are available in the following mounting styles: TB, TC, TD, J, JB, JJ, C, E, F, CB, G, D, DB, DD, H, HB, HH, BB, SB.

Basic Series 2HX Cylinders

Style T Mounting Envelope and Rod End Dimensions – See Table 1

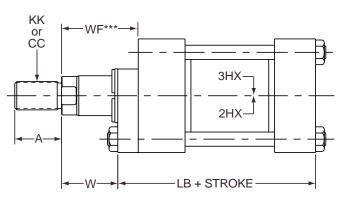


Table 1 – Envelope and Rod End Dimensions

For additional dimensions, consult Series 2H and Series 3H 7" and 8" Bore, of this catalog.

				Thread and Associated	Minimum W Dimension	tt	4 to 1
Bore	Rod No.	Rod Dia. mm	Α	KK Style 4	CC Style 8	LB Add Stroke	Design Factor (PSI)**
2	1	1					
2	2	1 ³ /8	1 5/8	1-14	1 ¹ /4 - 12	6 ¹ / ₂	3000
	1	1					
2 ¹ / ₂	2	1 ³ / ₄	2	1 ¹ / ₄ - 12	1 ¹ /2 - 12	6 ⁵ /8	3000
	3	1 ³ /8	1 ⁵ /8	1-14	1 ¹ /4 - 12	65/8	3000
	1	1 ³ /8	1 ⁵ /8	1-14	1 ¹ /4 - 12	7 ¹ / ₂	2130
3 ¹ / ₄	2	2	2 ¹ / ₄	1 ¹ / ₂ - 12	1 ³ / ₄ - 12	61/4	3000
	3	1 ³ / ₄	2	1 ¹ / ₄ - 12	1 ¹ / ₂ - 12	7 ¹ / ₂	3000
	1	1 ³ / ₄	2	1 ¹ / ₄ - 12	1 ¹ / ₂ - 12	7 ⁷ /8	2580
4	2	2 ¹ / ₂	3	1 ⁷ /8 - 12	2 ¹ / ₄ - 12	6 ⁵ /8	3000
	3	2	2 ¹ / ₄	11/2 - 12	1 ³ /4 - 12	6 ⁵ /8	3000
	1	2	2 ¹ /4	1 ¹ / ₂ - 12	1 ³ /4 - 12	7 ¹ /8	2510
-	2	3 ¹ / ₂	3 ¹ / ₂	2 ¹ / ₂ - 12	31/4 - 12	7 ¹ /8	3000
5	3	2 ¹ / ₂	3	17/8 - 12	21/4 - 12	7 ¹ /8	3000
	4	3	3 ¹ / ₂	2 ¹ / ₄ - 12	23/4 - 12	7 ¹ /8	3000
	1	2 ¹ / ₂	3	1 ⁷ /8 - 12	21/4 - 12	8 ³ /8	3000
0	2	4	4	3 - 12	3³/4 - 12	8 ³ /8	3000
6	3	3	3 ¹ / ₂	2 ¹ / ₄ - 12	23/4 - 12	8 ³ /8	3000
	4	3 ¹ / ₂	3 ¹ / ₂	2 ¹ / ₂ - 12	31/4 - 12	8 ³ / ₈	3000
	1	3	3 ¹ / ₂	21/4 - 12	23/4 - 12	9 ¹ / ₂	3000
	2	5	5	31/2 - 12	4 ³ / ₄ - 12	9 ¹ / ₂	3000
7*	3	3 ¹ / ₂	3 ¹ / ₂	2 ¹ / ₂ - 12	3³/4 - 12	9 ¹ / ₂	3000
	4	4	4	3 - 12	3³/4 - 12	9 ¹ / ₂	3000
	5	4 ¹ / ₂	4 ¹ / ₂	31/4 - 12	41/4 - 12	9 ¹ / ₂	3000
	1	3 ¹ / ₂	3 ¹ / ₂	21/2 - 12	31/4 - 12	10 ¹ / ₂	3000
	2	5 ¹ / ₂	5 ¹ /2	4 - 12	51/4 - 12	10 ¹ /2	3000
8*	3	4	4	3 - 12	3³/4 - 12	10 ¹ / ₂	3000
	4	4 ¹ / ₂	4 ¹ / ₂	31/4 - 12	41/4 - 12	10 ¹ / ₂	3000
	5			31/2 - 12	43/4 - 12	10 ¹ / ₂	3000

++Cylinders with rod sizes less than 2" require the addition of a 1¹/₄" spacer on the cap end of the piston to carry the wiper assembly. These LB dimensions reflect the additional length.

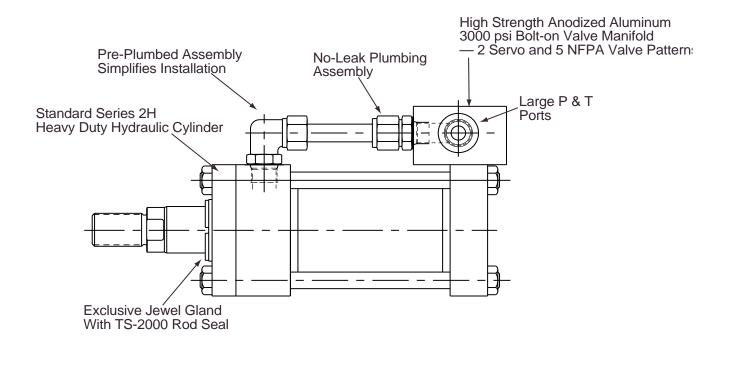
 ** The 4:1 design factor is based on the tensile strength of the piston to rod connection.

*Specify Series 3HX.

***For 7-8" Bore 3HX callout dimension WF.



Hydraulic Linear Actuator with Bolt-on Servo/NFPA Valve Manifold and Two Feedback Options



Innovative Motion Control

Parker's new Series 2HX is an integrated assembly that eliminates transducer mounting brackets, valve manifolds, plumbing and other items associated with using separate components. The versatility of the Series 2HX allows you to design cost effective actuators for accurate position and velocity control for your specific application.

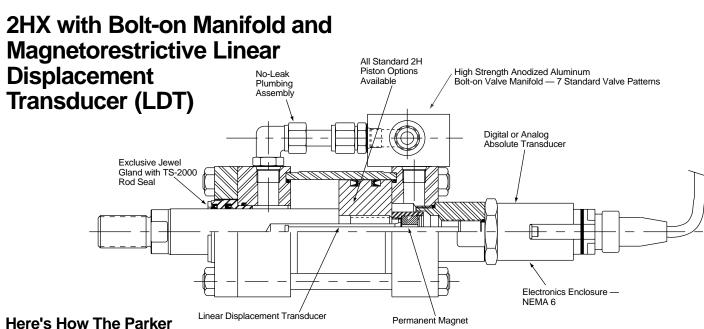
Features and Benefits

- Minimum hydraulic line runs with closed cylinder and valve coupling
- Simplified machine design with integrated components
- Eliminates the need for limit switches, deceleration valves, shock absorbers, and mechanical linkages in many applications
- Minimum interference with standard mounting dimensions
- Manifold may be mounted on head or cap end at any position not occupied by a mount

- 7 standard valve patterns
- Integral mounted valve eliminates assembly time and fittings.
- Custom manifolds available consult factory

Custom Options Available

- Low friction rod gland see page 193 for specifications
- Hi-Load Piston see Section C, page 4
- Protective feedback enclosures
- Intrinsically safe modifications
- Feedback devices in stock for quick delivery of common stroke lengths
- Closed-loop control for maximum productivity
- Performance-tested actuators
- Complete, tested cylinder/feedback assemblies customized to your needs

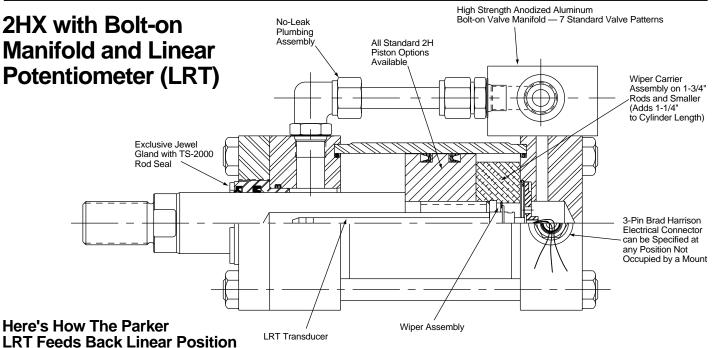


LDT Feeds Back Linear Position

The linear displacement transducer is rigidly attached to the cap end of the cylinder, and runs the full stroke length inside a hollow piston rod. A magnet is attached to the cylinder piston. As the piston moves through the stroke, the transducer is able to define the exact position of the magnet by measuring the time interval between the initiation and the return of the strain pulses launched in the transducer wave guide.

For LDT specifications see page 186.

For base cylinder dimensions see page B-149.



The LRT feedback device is essentially a linear potentiometer which provides a cost effective solution for applications where a contacting device is acceptable. The potentiometer is fixed to the rear cap of the cylinder and runs the full length inside a hollow piston rod. The wiper assembly is fixed to the piston. As the piston moves

through the stroke, the wiper voltage changes in proportion to the cylinder position.

For specifications on the LRT see page 191.

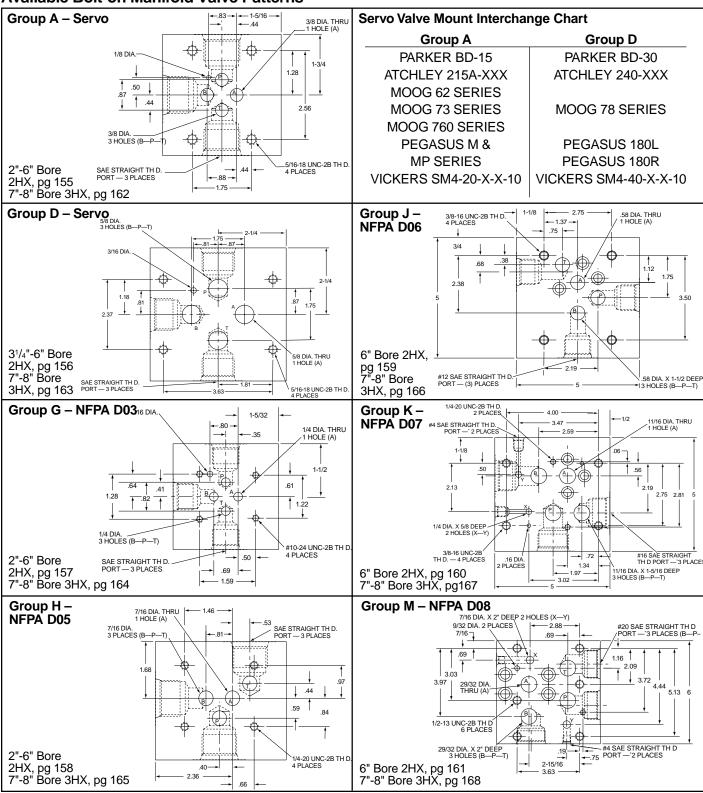
For base cylinder dimensions see page B-151.



В

Bolt-on Manifolds

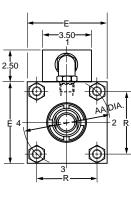
Parker Series 2HX cylinders are available with Bolt-on Manifolds. Manifolds can be mounted on the head or cap end of a Parker Series 2H or 3H cylinders. For availability of manifolds by bore size, see pages 155-169 of this catalog.

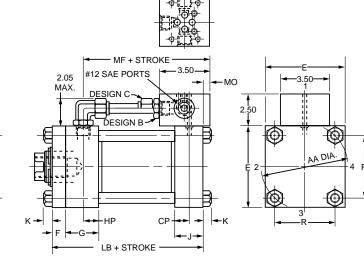


Available Bolt-on Manifold Valve Patterns

2HX with Group A **Bolt-on Manifold** Cap End

(Parker BD-15 Servo)

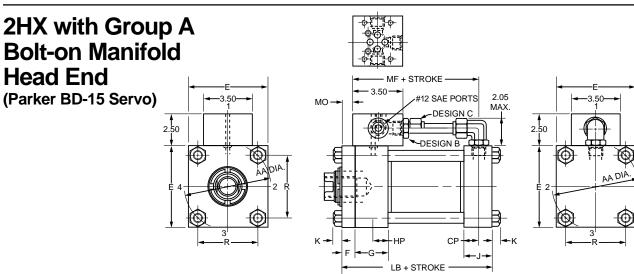




	Group A/Parker BD-15 Valve Manifold, Cap End Mounted, Series 2HX Cylinder													Design C*
Bore	Bore MO E MF CP HP F G J K AA R LB												Min. Stroke	Min. Stroke
2.00	.562	3.000	4.187	.750	.750	.625	1.75	1.50	.438	2.9	2.05	5.250	1.625	2.875
2.50	.562	3.500	4.312	.750	.750	.625	1.75	1.50	.438	3.6	2.55	5.375	1.500	2.750
3.25	.468	4.500	4.875	.906	.906	.750	2.00	1.75	.562	4.6	3.25	6.250	.875	2.125
4.00	.468	5.000	5.125	.906	.906	.875	2.00	1.75	.562	5.4	3.82	6.625	.625	1.875
5.00	.468	6.500	5.625	.906	.906	.875	2.00	1.75	.812	7.0	4.95	7.125	.125	1.375
6.00†													0	.875

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes.

†Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI.



	Group A/Parker BD-15 Valve Manifold, Head End Mounted, Series 2HX Cylinder													Design C*
Bore	Bore MO E MF CP HP F G J K AA R LB											Min. Stroke	Min. Stroke	
2.00	.312	3.000	4.187	.750	.750	.625	1.75	1.50	.438	2.9	2.05	5.250	1.625	2.875
2.50	.312	3.500	4.312	.750	.750	.625	1.75	1.50	.438	3.6	2.55	5.375	1.500	2.750
3.25	.532	4.500	4.875	.906	.906	.750	2.00	1.75	.562	4.6	3.25	6.250	.875	2.125
4.00	.657	5.000	5.125	.906	.906	.875	2.00	1.75	.562	5.4	3.82	6.625	.625	1.875
5.00	.657	6.500	5.625	.906	.906	.875	2.00	1.75	.812	7.0	4.95	7.125	.125	1.375
6.00†	.938	7.500	6.187	1.000	1.000	1.000	2.25	2.25	.875	8.1	5.73	8.375	0	.875

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes.

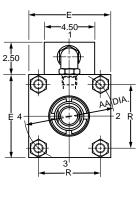
†Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI. Β

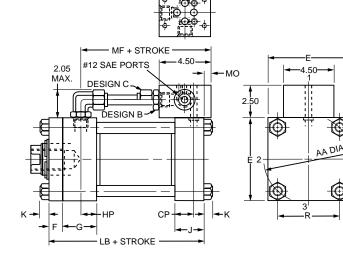
For Cylinder Division Plant Locations - See Page II.



2HX with Group D Bolt-on Manifold Cap End

(Parker BD-30 Servo)

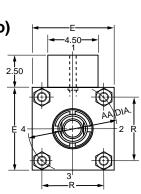




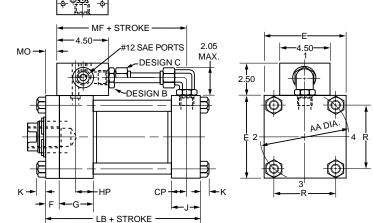
	Group D/Parker BD-30 Valve Manifold, Cap End Mounted, Series 2HX Cylinder													Design C*
Bore	Bore MO E MF CP HP F G J K AA R LB											Min. Stroke	Min. Stroke	
3.25	.531	4.500	4.937	.906	.906	.750	2.00	1.75	.562	4.6	3.25	6.250	1.875	3.125
4.00	.531	5.000	5.187	.906	.906	.875	2.00	1.75	.562	5.4	3.82	6.625	1.625	2.875
5.00	.531	6.500	5.687	.906	.906	.875	2.00	1.75	.812	7.0	4.95	7.125	1.125	2.375
6.00†	.125	7.500	6.250	1.000	1.000	1.000	2.25	2.25	.875	8.1	5.73	8.375	.500	1.750

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. †Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI.

2HX with Group D Bolt-on Manifold Head End (Parker BD-30 Servo)

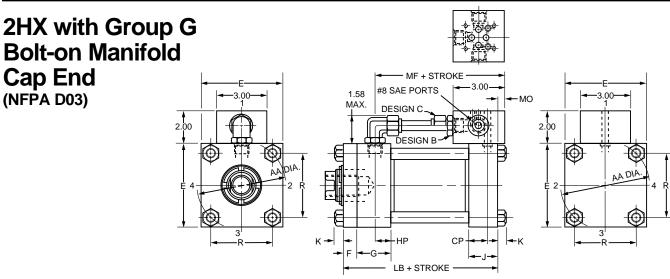






	Group A/Parker BD-30 Valve Manifold, Head End Mounted Series 2HX Cylinder													Design C*
Bore	Bore MO E MF CP HP F G J K AA R LB											Min. Stroke	Min. Stroke	
3.25	.469	4.500	4.937	.906	.906	.750	2.00	1.75	.562	4.6	3.25	6.250	1.875	3.125
4.00	.594	5.000	5.187	.906	.906	.875	2.00	1.75	.562	5.4	3.82	6.625	1.625	2.875
5.00	.594	6.500	5.687	.906	.906	.875	2.00	1.75	.812	7.0	4.95	7.125	1.125	2.375
6.00†	6.00† .875 7.500 6.250 1.000 1.000 1.000 2.25 2.25 .875 8.1 5.73 8.375												.500	1.750

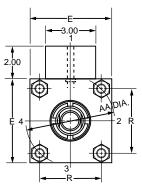
*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. †Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI.

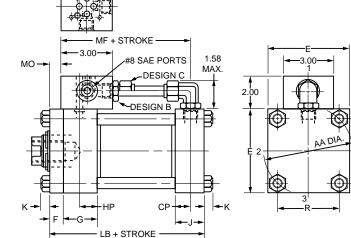


		G	roup G/NF	PA D03 Va	alve Manif	old, Cap E	Ind Moun	ted Series	2HX Cylir	nder			Design B*	Design C*	
Bore	МО	Е	MF	СР	HP	F	G	J	к	AA	R	LB	Min. Stroke	Min. Stroke	
2.00															
2.50	.406	5.375	.750	1.625											
3.25	.312	4.500	4.718	.906	.906	.750	2.00	1.75	.562	4.6	3.25	6.250	.250	1.000	
4.00	.312	5.000	4.968	.906	.906	.875	2.00	1.75	.562	5.4	3.82	6.625	0	.750	
5.00	.312	6.500	5.468	.906	.906	.875	2.00	1.75	.812	7.0	4.95	7.125	0	.250	
6.00†	N/A	7.500	6.031	1.000	1.000	1.000	2.25	2.25	.875	8.1	5.73	8.375	0	0	

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. †Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI.

2HX with Group G Bolt-on Manifold Head End (NFPA D03)





		G	iroup G/N	FPA D03 V	alve Mani	fold, Head	End Mou	inted, Seri	es 2HX Cy	linder			Design B*	Design C*
Bore	мо	Е	MF	СР	HP	F	G	J	к	AA	R	LB	Min. Stroke	Min. Stroke
2.00	.468	3.000	4.031	.750	.750	.625	1.75	1.50	.438	2.9	2.05	5.250	.875	1.750
2.50	.468	3.500	4.156	.750	.750	.625	1.75	1.50	.438	3.6	2.55	5.375	.750	1.625
3.25	.688	4.500	4.718	.906	.906	.750	2.00	1.75	.562	4.6	3.25	6.250	.250	1.000
4.00	.813	5.000	4.968	.906	.906	.875	2.00	1.75	.562	5.4	3.82	6.625	0	.750
5.00	.813	6.500	5.468	.906	.906	.875	2.00	1.75	.812	7.0	4.95	7.125	0	.250
6.00†	1.109	7.500	6.031	1.000	1.000	1.000	2.25	2.25	.875	8.1	5.73	8.375	0	0

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. †Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI.

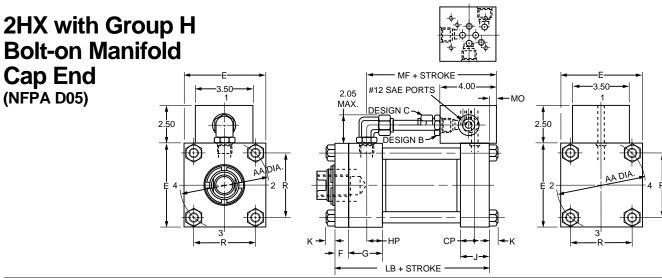
В



Cap End

(NFPA D05)

Series 2HX **Electrohydraulic Actuators**

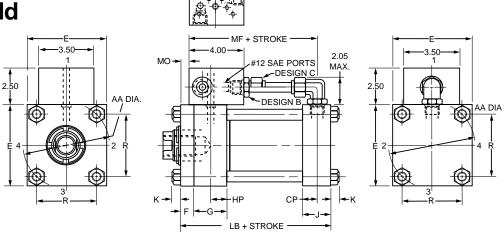


		G	Froup H/N	FPA D05 V	alve Mani	fold, Cap	End Moun	ted Series	a 2HX Cyli	nder			Design B*	Design C*
Bore	МО	Е	MF	СР	HP	F	G	J	к	AA	R	LB	Min. Stroke	Min. Stroke
2.00	.891	3.000	4.51	.750	.750	.625	1.750	1.500	.438	2.9	2.05	5.250	1.750	3.000
2.50	.891	3.500	4.64	.750	.750	.625	1.750	1.500	.438	3.6	2.55	5.375	1.625	2.875
3.25	.797	4.500	5.2	.906	.906	.750	2.000	1.750	.562	4.6	3.25	6.250	1.125	2.375
4.00	.797	5.000	5.45	.906	.906	.875	2.000	1.750	.562	5.4	3.82	6.625	.875	2.125
5.00	.797	6.500	5.95	.906	.906	.875	2.000	1.750	.812	7.0	4.95	7.125	.375	1.625
6.00†	.391	7.500	6.51	1.000	1.000	1.000	2.250	2.250	.875	8.1	5.73	8.375	0	1.000

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes.

†Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI.

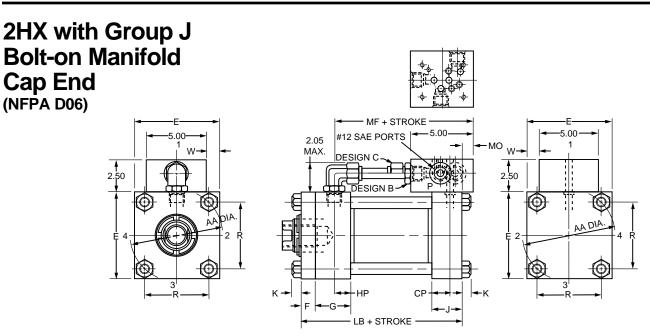




		Gr	oup H/NFI	PA D05 Va	lve Manifo	old, Head	End Moun	ted Series	3 2HX Cyli	nder			Design B*	Design C*
Bore	мо	Е	MF	СР	HP	F	G	J	к	AA	R	LB	Min. Stroke	Min. Stroke
2.00	0	3.000	4.51	.750	.750	.625	1.75	1.50	.438	2.9	2.05	5.250	1.750	3.000
2.50	0	3.500	4.64	.750	.750	.625	1.75	1.50	.438	3.6	2.55	5.375	1.625	2.875
3.25	.203	4.500	5.20	.906	.906	.750	2.00	1.75	.562	4.6	3.25	6.250	1.125	2.375
4.00	.328	5.000	5.45	.906	.906	.875	2.00	1.75	.562	5.4	3.82	6.625	.875	2.125
5.00	.328	6.500	5.95	.906	.906	.875	2.00	1.75	.812	7.0	4.95	7.125	.375	1.625
6.00†	.609	7.500	6.51	1.000	1.000	1.000	2.25	2.25	.875	8.1	5.73	8.375	0	1.000

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes.

†Consult Factory for 6" Bore DD Mount. Standard Operating Pressure is 3000 PSI.



			Group J/N	FPA D06 \	/alve Man	ifold, Cap	End Mou	nted Seri	es 2HX (Sylinder				Design B*	Design C*
Bore	Bore MO E MF CP HP F G J K AA R LB														Min. Stroke
6.00	.620	7.500	6.745	1.000	1.000	1.000	2.250	2.250	.875	8.100	5.730	8.375	1.250	.625	1.750

(NFPA D06)

Consult Factory for DD Mount. Standard Operating Pressure is 3000 PSI.

2HX with Group J **Bolt-on Manifold Head End** MF + STROKE MO-5 00 00 5.00 #12 SAE 2.05 PORTS MAX. -DESI W 2.50 2.50 DESIGN AA DIA. AA DIA З CP G LB + STROKE

		Grou	p J/NFPA	D06 Valve	Bolt-on M	lanifold, H	ead End I	Mounted,	Series 2	HX Cylir	der			Design B*	Design C*
Bore	ore MO E MF CP HP F G J K AA R W L														Min. Stroke
6.00	.380	7.500	6.745	1.000	1.000	1.000	2.25	2.25	.875	8.1	5.73	1.250	8.375	.625	1.750

Design A (not shown) used only if stroke is shorter than minimum stroke shown for "Design B" on chart; consult factory, engineering required. *Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. Consult Factory for DD Mount. Standard Operating Pressure is 3000 PSI. *Design C used only for strokes in "Design C" column on chart and greater strokes.

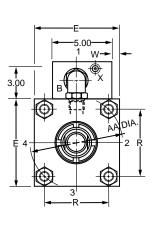
Β

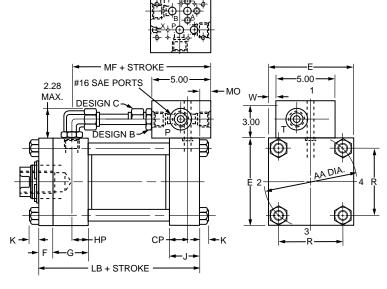
For Cylinder Division Plant Locations - See Page II.



2HX with Group K Bolt-on Manifold Cap End

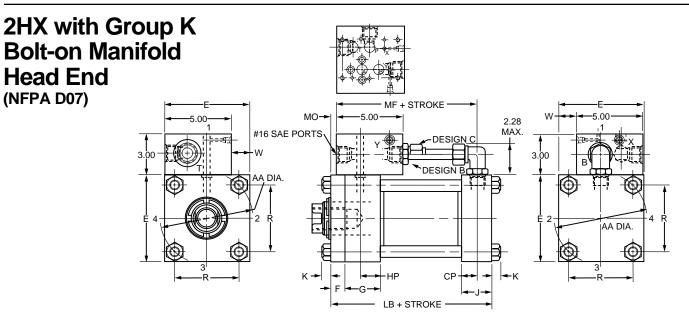
(NFPA D07)





			Group K/	NFPA D07	Valve Ma	nifold, Cap	End Mou	unted Ser	ies 2HX	Cylinder				Design B*	Design C*
Bore	ore MO E MF CP HP F G J K AA R LB W														Min. Stroke
6.00	.590	7.500	6.715	1.000	1.000	1.000	2.250	2.250	.875	8.100	5.730	8.375	.435	1.104	2.285

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. Consult Factory for DD Mount. Standard Operating Pressure is 3000 PSI.

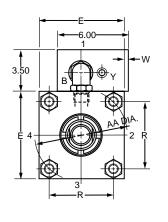


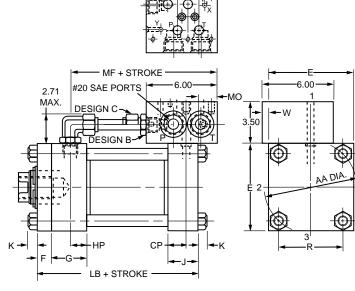
		Grou	ıp J/NFPA	D07 Valve	Bolt-on M	lanifold, ⊦	lead End	Mounted	, Series 2	2HX Cylii	nder			Design B*	Design C*
Bore	Bore MO E MF CP HP F G J K AA R W LI														Min. Stroke
6.00	.410	7.500	6.715	1.000	1.000	1.000	2.25	2.25	.875	8.1	5.73	2.065	8.375	1.104	2.285

Design A (not shown) used only if stroke is shorter than minimum stroke shown for "Design B" on chart; consult factory, engineering required.*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart.Consult Factory for DD Mount.*Design C used only for strokes in "Design C" column on chart and greater strokes.Standard Operating Pressure is 3000 PSI.

2HX with Group M **Bolt-on Manifold** Cap End

(NFPA D08)





			Group M/	NFPA D08	Valve Ma	nifold, Ca	o End Mo	unted Sei	ries 2HX	Cylinder				Design B*	Design C*
Bore	Bore MO E MF CP HP F G J K AA R LB W														Min. Stroke
6.00	1.566	7.500	7.816	1.286	1.125	1.000	2.250	2.250	.875	8.100	5.730	8.375	.250	1.75	3.00

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes.

Consult Factory for DD Mount. Standard Operating Pressure is 3000 PSI.

2HX with Group M **Bolt-on Manifold Head End** (NFPA D08) MF + STROKE #20 SAE PORTS 6.00 6 00 2.71 MO--MAX 3.50 DESIGN AA DIA AA DIA 2 CF G LB + STROKE

			Group M/I	NFPA D08	Valve Bol	t-on Manif	old, Head	End Mou	unted, Se	eries 2HX	Cylinde	er		Design B*	Design C*
Bore	ore MOI E MF CP HP F G J K AA R W† LB													Min. Stroke	Min. Stroke
6.00	.500	7.500	7.813	1.188	1.220	1.000	2.25	2.25	.875	8.1	5.73	1.755	8.375	1.75	3.00

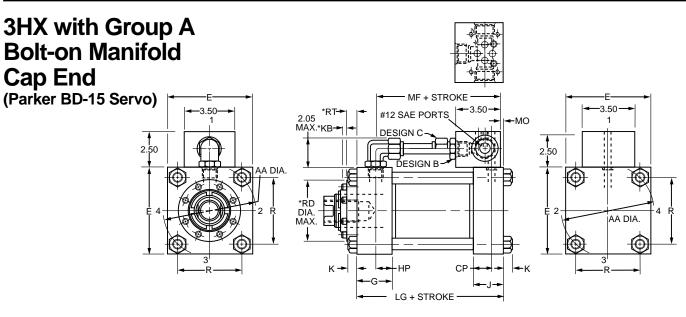
Design A (not shown) used only if stroke is shorter than minimum stroke shown for "Design B" on chart; consult factory, engineering required. *Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. Consult Factory for DD Mount. *Design C used only for strokes in "Design C" column on chart and greater strokes. BOM will overhang past head face.

Standard Operating Pressure is 3000 PSI. †BOM will overhang past head face.

Β

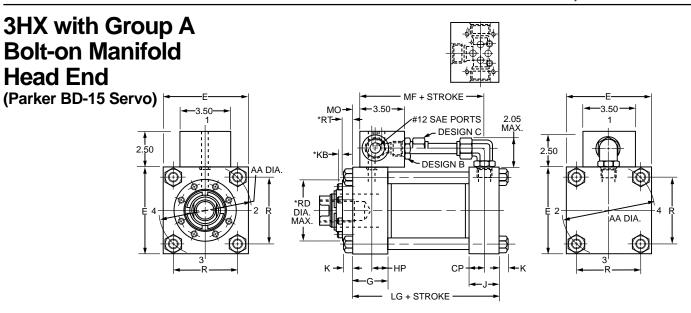
Cylinder 161

For Cylinder Division Plant Locations - See Page II.



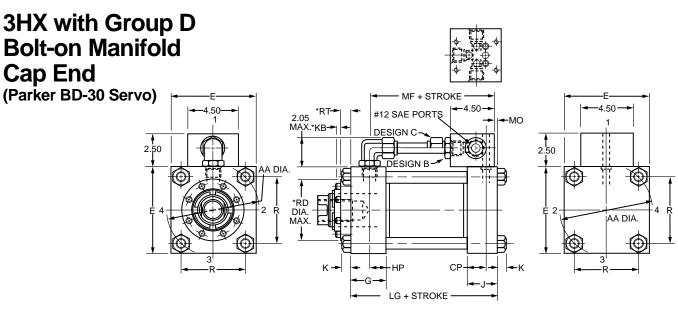
		Group A	/Parker B	D-15 Valve	Manifold,	Cap End I	Mounted S	eries 3HX	Cylinder			Design B*	Design C*
Bore	МО	LG	Min. Stroke	Min. Stroke									
7.00	.188	8.500	6.813	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	0	.375
8.00	.313	9.500	7.563	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	N/A	0

*See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.



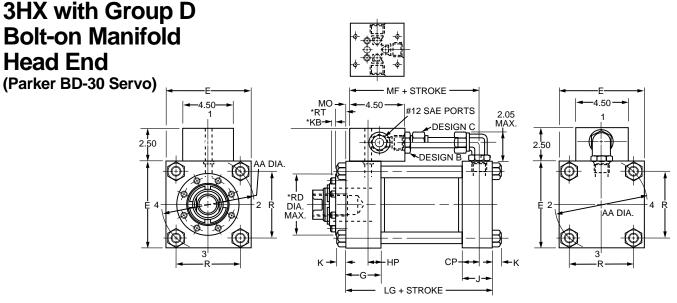
		Group A/	Parker BD	-15 Valve I	Manifold, H	lead End I	Mounted S	eries 3HX	Cylinder			Design B*	Design C*
Bore	мо	LG	Min. Stroke	Min. Stroke									
7.00	.188	8.500	6.813	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	0	.375
8.00	.313	9.500	7.563	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	N/A	0

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.



		Group D	/Parker BI	0-30 Valve	Manifold,	Cap End M	lounted S	eries 3HX	Cylinder			Design B*	Design C*
Bore													Min. Stroke
7.00	.125	8.500	6.875	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	0	1.250
8.00	.250	9.500	7.625	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	0	.500

*See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.



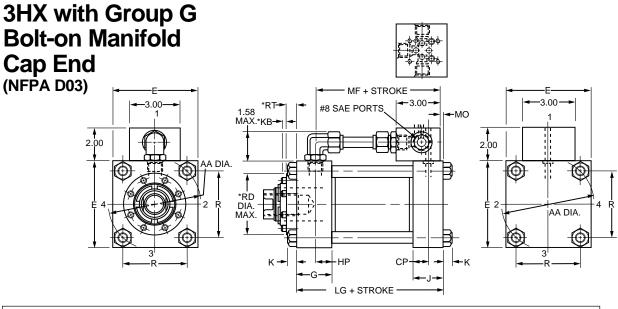
		Group D/	Parker BD	-30 Valve I	Manifold, I	lead End I	Mounted S	eries 3HX	Cylinder			Design B*	Design C*
Bore													Min. Stroke
7.00	.125	8.500	6.875	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	0	1.250
8.00	.250	9.500	7.625	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	0	.500

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.

For Cylinder Division Plant Locations - See Page II.

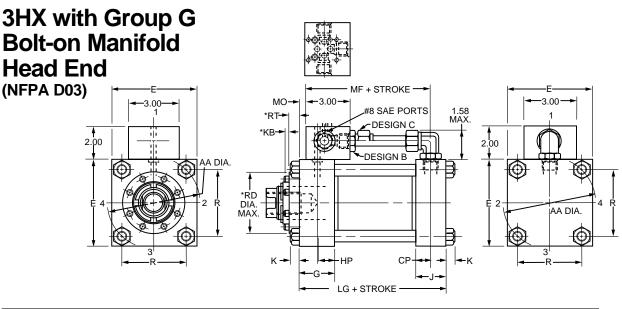


В



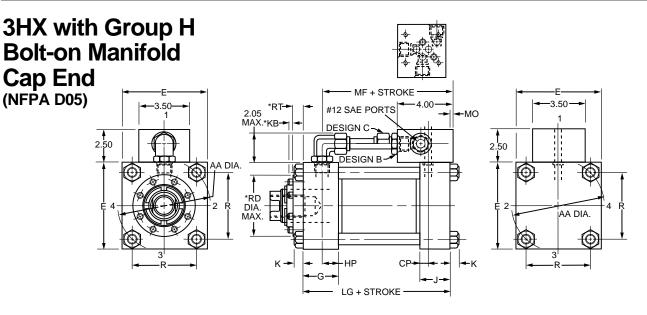
		Group	G/NFPA D	03 Valve N	lanifold, C	ap End Mo	ounted Ser	ies 3HX C	ylinder				
Bore													
7.00	.344	8.500	6.656	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50		
8.00	.469	9.500	7.406	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50		

*See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.



		Group G	6/NFPA D0	3 Valve Ma	nifold, He	ad End Mo	ounted Ser	ies 3HX C	ylinder					
Bore														
7.00	.344	8.500	6.656	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50			
8.00	.469	9.500	7.406	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50			

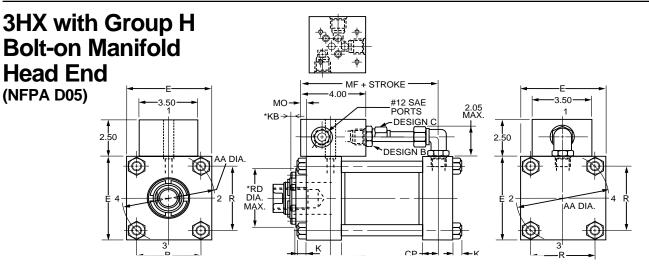
*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.



		Group	H/NFPA D	005 Valve N	lanifold, C	ap End M	ounted Se	ries 3HX C	Sylinder			Design B*	Design C*
Bore													
7.00	.141	8.500	7.141	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	0	.50
8.00	.016	9.500	7.891	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	N/A	0
			1		1	1			1				

BOM will overhang cap face

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.



		Group	H/NFPA DO	5 Valve Ma	anifold, He	ad End M	ounted Se	ries 3HX C	Cylinder			Design B*	Design C*
Bore												Min. Stroke	Min. Stroke
7.00	.141	8.500	7.141	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	0	.50
8.00	.016	9.500	7.891	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	N/A	0

BOM will overhang cap face

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.

For Cylinder Division Plant Locations – See Page II.

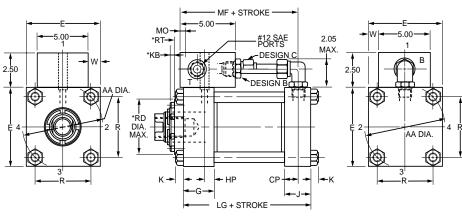


3HX with Group J **Bolt-on Manifold** Cap End (NFPA D06) MF + STROKE -5.00 *RT #12 SAE PORTS 5.00 2.05 MAX.*KB-МО SIGN C 2.50 ESIGN A DIA *RD DIA AA DIA. MAX ſŒ CP κ LG + STROKE

	Group J/NFPA D06 Valve Manifold, Cap End Mounted Series 3HX Cylinder													
Bore MO														
7.00 .375	8.500	7.375	1.250	1.250	2.750	2.750	1.000	9.300	6.580	8.500	1.750	.25	1.125	
8.00 .250	9.500	8.125	1.375	1.375	3.000	3.000	1.062	10.600	7.500	9.500	2.250	0	.375	

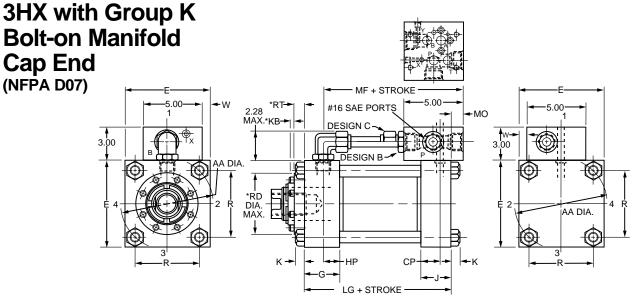
*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. BOM will overhang past cap face. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.

3HX with Group J Bolt-on Manifold Head End (NFPA D06)



		Group J	/NFPA D0	6 Valve Bo	lt-on Mani	fold, Head	End Mou	nted, Serie	es 3HX C	ylinder			Design B*	Design C*
Bore	МО	Е	MF	СР	HP	G	J	к	AA	R	LG	w	Min. Stroke	Min. Stroke
7.00	.375	8.500	7.375	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	1.75	.250	1.125
8.00	.250	9.500	8.125	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	2.25	0	.375

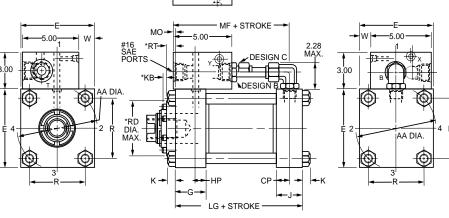
*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. BOM will overhang past head face. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.



		Gr	oup K/NFF	PA D07 Valv	ve Manifol	d, Cap En	d Mounted	Series 3	HX Cyline	der			Design B*	Design C*
Bore														
7.00	.344	8.500	7.344	1.250	1.250	2.750	2.750	1.000	9.300	6.580	8.500	.935	.750	1.750
8.00	.219	9.500	8.094	1.375	1.375	3.000	3.000	1.062	10.600	7.500	9.500	1.435	0	1.000
*Deelan D	upped only	if atralia fa	المناه الم	on "Deciar	D" and "C		in strake		n ahart	*0.04	Dorkor	Carica 21	l for dimon	alana

*See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.

3HX with Group K Bolt-on Manifold Head End (NFPA D07)

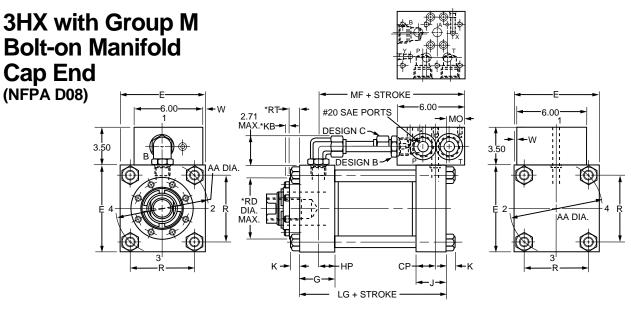


		Group K	/NFPA D07	Valve Bol	lt-on Mani	fold, Head	End Mour	nted, Serie	es 3HX C	ylinder			Design B*	Design C*
Bore												Min. Stroke	Min. Stroke	
7.00	.344	8.500	7.344	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	2.565	.750	1.75
8.00	.219	9.500	8.094	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	3.065	0	1.000

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. BOM will overhang past head face. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.

For Cylinder Division Plant Locations – See Page II.





		Gi	oup M/NF	PA D08 Va	lve Manifo	ld, Cap En	d Mounte	d Series 3	BH Cylind	ler			Design B*	Design C*
Bore														
7.00	1.031	8.500	8.031	1.250	1.250	2.750	2.750	1.000	9.300	6.580	8.500	.250	1.375	2.625
8.00	.906	9.500	8.781	1.375	1.375	3.000	3.000	1.062	10.600	7.500	9.500	.750	.625	1.938
										*•		.		

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. BOM will overhang past cap face. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.

3HX with Group M Bolt-on Manifold Head End (NFPA D08)

3

MF + STROKE мо #20 SAE PORTS 6.00 2.71 R. MA. DESIGN C 3.00 *KB A DIA *RD DIA AA DIA MAX к-CF HE -ĸ G LG + STROKE

		Group M	I/NFPA D0	8 Valve Bo	lt-on Mani	fold, Head	End Mour	nted, Serie	es 3HX C	ylinder			Design B*	Design C*
Bore	мо	Е	MF	СР	HP	G	J	к	AA	R	LG	w	Min. Stroke	Min. Stroke
7.00	1.031	8.500	8.031	1.250	1.250	2.75	2.75	1.000	9.3	6.58	8.50	2.250	1.375	2.625
8.00	.906	9.500	8.781	1.375	1.375	3.00	3.00	1.062	10.6	7.50	9.50	2.750	.625	1.938

*Design B used only if stroke falls in between "Design B" and "Design C" min. stroke columns on chart. *Design C used only for strokes in "Design C" column on chart and greater strokes. BOM will overhang past head face. *See Parker Series 3H for dimensions. Standard Operating Pressure is 3000 PSI. Consult Factory for DD Mount.

Series 2HX and 3HX Mounting Dimensions

The Parker Series 2HX and 3HX Bolt-on Manifold option does not affect the standard envelope and mounting dimensions of the base Parker Series 2H or 3H Heavy Duty Hydraulic Cylinder except where noted on previous pages of this catalog. All standard Parker Series 2H and 3H mounting styles are available with the Series 2HX and 3HX Bolt-on Manifold option. For base cylinder dimensions refer to the Parker Series 2H and 3H sections of the Parker Actuator Catalog.

Series 2HX and 3HX Bolt-on Manifolds may be specified at any

head or cap position which does not interfere with the mounting style selected. For available manifold mounting positions see Table A on page B-147. Manifold position must be specified when ordering.

For Parker mounting style DD refer to the minimum and maximum XI dimensions in Table 1 and Table 2 below.

Consult Factory for 6" Bore 2HX and 7"-8" Bore 3HX with Style DD Mounts.

Table 1 – Head End Mounted Bolt-on Manifold Maximum and Minimum 'XI' Location for Style DD Mounts

Series	Bore	МХ			В	MN olt-on Manifol	d		
			Group A	Group D	Group G	Group H	Group J	Group K	Group M
	2	3	4.563	N/A	4.219	4.734	N/A	N/A	N/A
	2.5	3.125	4.563	N/A	4.219	4.734	N/A	N/A	N/A
	3.25	3.5	5.032	5.969	4.688	5.203	N/A	N/A	N/A
2HX	4	3.875	5.156	6.094	4.813	5.328	N/A	N/A	N/A
	5	4.375	5.156	6.094	4.813	5.328	N/A	N/A	N/A
	6				CONSULT	FACTORY			
знх	7				CONSULT	FACTORY			
5117	8				CONSULT	FACTORY			
	2	2.25	N/A	N/A	3.906	N/A	N/A	N/A	N/A
	2.5	2.375	N/A	N/A	3.906	N/A	N/A	N/A	N/A
	3.25	2.625	4.875	N/A	4.531	5.047	N/A	N/A	N/A
3LX	4	2.625	4.875	N/A	4.531	5.047	N/A	N/A	N/A
	5	2.875	4.875	N/A	4.531	5.047	N/A	N/A	N/A
	6	3	5.375	6.313	5.031	5.547	N/A	N/A	N/A
	8	3.125	5.375	6.313	5.031	5.547	N/A	N/A	N/A

Maximum and Minimum 'XI' Location

2H & 3L Series Min. 'XI' = W + MN Max. 'XI' = W + MX + Stroke **3H Series** Min. 'XI' = WF + MN Max. 'XI' = W + MX + Stroke

Table 2 - Cap End Mounted Bolt-on Manifold Maximum and Minimum 'XI' Location for Style DD Mounts

Series	Bore	MN			В	MX olt-on Manifol	d		
			Group A	Group D	Group G	Group H	Group J	Group K	Group M
	2	3.125	1.562	N/A	1.906	1.391	N/A	N/A	N/A
	2.5	3.125	1.687	N/A	2.031	1.516	N/A	N/A	N/A
	3.25	3.75	2.218	1.281	2.563	2.047	N/A	N/A	N/A
2HX	4	3.875	2.593	1.656	2.938	2.422	N/A	N/A	N/A
	5	3.875	3.093	2.156	3.438	2.922	N/A	N/A	N/A
	6				CONSULT	FACTORY		•	
знх	7				CONSULT	FACTORY			
307	8				CONSULT	FACTORY			
	2	2.625	N/A	N/A	0.969	N/A	N/A	N/A	N/A
	2.5	2.625	N/A	N/A	1.094	N/A	N/A	N/A	N/A
-	3.25	3.375	1.125	N/A	1.469	0.953	N/A	N/A	N/A
3LX	4	3.375	1.125	N/A	1.469	0.953	N/A	N/A	N/A
	5	3.375	1.375	N/A	1.719	1.203	N/A	N/A	N/A
	6	4	1.625	0.687	1.969	1.453	N/A	N/A	N/A
	8	4	1.75	0.812	2.093	1.578	N/A	N/A	N/A

Maximum and Minimum 'XI' Location

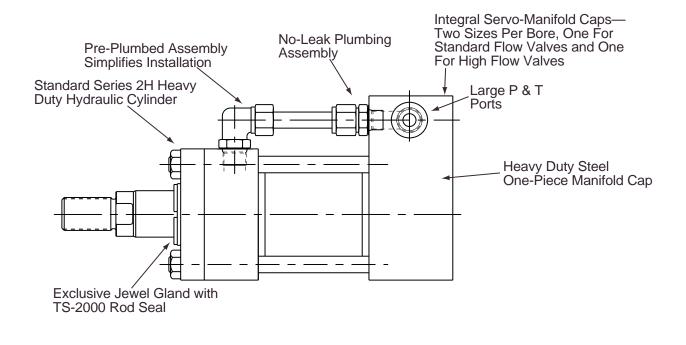
2H & 3L Series Min. 'XI' = W + MN Max. 'XI' = W + MX + Stroke **3H Series** Min. 'XI' = WF + MN Max 'XI' = W + MX + S

Max. 'XI' = W + MX + Stroke

For Cylinder Division Plant Locations - See Page II.



Hydraulic Linear Actuator with Integral Servo/NFPA Valve Manifold and Two Feedback Options



Innovative Motion Control

Parker's new Series 2HX is an integrated assembly that eliminates transducer mounting brackets, valve manifolds, plumbing and other items associated with using separate components. The versatility of the Series 2HX allows you to design an actuator for accurate position and velocity control for your specific application.

Features and Benefits

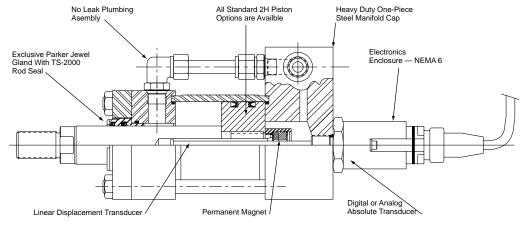
- Minimum hydraulic line runs with close cylinder and valve coupling.
- Simplified machine design with integrated components.
- Eliminates need for limit switches, deceleration valves, shock absorbers, and mechanical linkages in many applications.
- Minimum interference with standard mounting dimensions.
- Blank manifold caps can be machined to meet customer valve mounting specifications.

- Integral mounted valve eliminates assembly time and fittings.
- Custom supplied servo valve and equivalent feedback device can be integrated into the cylinder.

Custom Options Available

- Low friction rod gland see page 193 for specifications.
- Low friction piston see page C36 for specifications.
- Protective feedback enclosures.
- Intrinsically safe modifications.
- Feedback devices in stock for quick delivery of common stroke lengths.
- Closed-loop control for maximum productivity.
- Performance-tested actuators.
- Complete, tested cylinder/feedback assemblies customized to your needs.

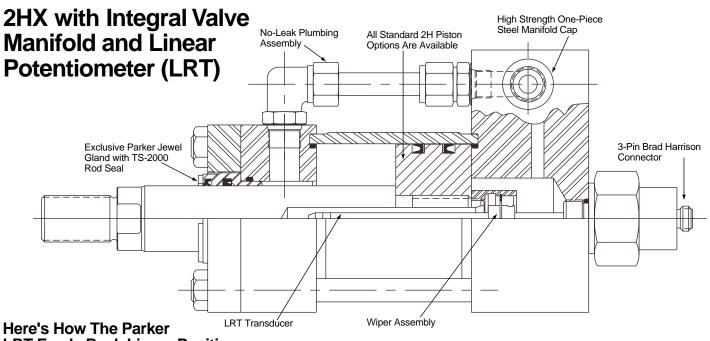
2HX with Integral Valve Manifold and Magnetorestrictive Linear Displacement Transducer (LDT)



Here's How The Parker LDT Feeds Back Linear Position

The linear displacement transducer is rigidly attached to the cap end of the cylinder, and runs the full stroke length inside a hollow piston rod. A magnet is attached to the cylinder piston. As the piston moves through the stroke, the transducer is able to define the exact position of the magnet by measuring the time interval between the initiation and the return of strain pulses launched in the transducer wave guide.

For LDT specifications see page 186.



LRT Feeds Back Linear Position

The LRT feedback device is essentially a linear potentiometer which provides a cost effective solution for applications where a contacting device is acceptable. The potentiometer is fixed to the rear cap of the cylinder and runs the full length inside a hollow piston rod. The wiper assembly is fixed to the piston. As the piston moves through the stroke, the wiper voltage changes in proportion to the cylinder position.

For specifications on the LRT see page 191.

В



cap end at position #1. Special Valve Patterns may be

supplied — consult factory. Integral Valve Mounts are

available on 2" through 5" Bores.

Integral Manifolds

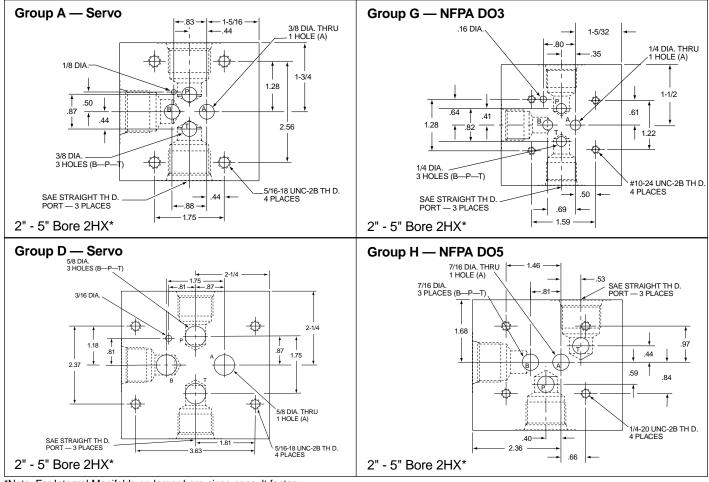
Parker Series 2HX cylinders are available with integral valve mounts. There are four standard patterns available. All Integral Valve Patterns will be supplied on the

Servo Valve Mounting Interchange Chart

(All Valves in Each Group Have Interchangeable Mounts)

Group A	Group D
Parker BD-15	Parker BD-30
Atchley 215A-XXX	Atchley 240-XXX
MOOG 62 Series	
MOOG 73 Series	MOOG 78 Series
MOOG 760 Series	
Pegasus M & MP Series	Pegasus 180L Pegasus 180R
Vickers SM4-20-X-X-10	Vickers SM4-40-X-X-10

Standard Integral Valve Patterns



*Note: For Integral Manifolds on larger bore sizes consult factory.

2HX with Integral Manifold — General Information

Bore & Rod Diameters

Standard bore and rod diameters for electro-hydraulic actuators are shown on the following pages of this catalog. Other sizes can be supplied as specials on request.

For heavy-duty or high-cycling applications, the use of a larger rod diameter is recommended. Refer to Section C, page 82 for proper sizing of piston rods.

Stroke Length

If an integrally mounted position transducer is specified, the maximum stroke length will normally be limited by the type of transducer.

Stop Tube

An internal stop tube (piston spacer) is recommended in cases where the combination of stroke length and mounting

Pressure Ratings

Series 2HX integral manifold actuators have a nominal working pressure of 3000 psi. Recommended maximum working pressures for 2HX integral manifold actuators with Feedback option (LDT or LRT) are given below. These pressure ratings are given as a guide for typical applications. For applications involving high cycle rates, high frequencies or shock loads, please consult factory.

Parker Series 2HX Pressure Ratings

		J	4 to 1
Bore	Rod No.	Rod Dia. MM	Design Factor (PSI)*
2	1	1	Not Available†
	2	1 ³ /8	3000
	1	1	Not Available†
2 ¹ / ₂	2	1 ³ /4	3000
	3	1 ³ /8	3000
	1	1 ³ /8	2130
31/4	2	2	3000
	3	1 ³ /4	3000
	1	1 ³ /4	2580
4	2	2 ¹ / ₂	3000
	3	2	3000
	1	2	2510
5	2	31/2	3000
5	3	2 ¹ / ₂	3000
	4	3	3000

*The 4 to 1 design factor is based on the tensile strength of the piston to rod connection.

†A mini LRT (MLRT) is available for 1" Rods - Consult Factory.



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style option could result in excessive bearing loads on the piston or rod gland. Please refer to Section C of this catalog.

A stop tube may also be used to eliminate the need for an extended rod end with the LDT Model.

Mounting Styles

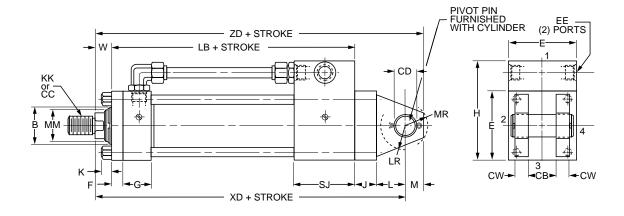
Mounting styles available as standard on 2HX integral manifold actuators are shown in this catalog. If other mountings are required, please consult factory.

Cushioning

On cylinders fitted with integral feedback, cushioning is available as a standard option at both ends. Double rod (equal area) cylinders can have the normal cushion option at both ends.

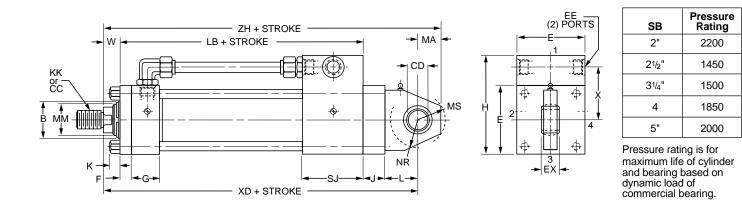
Cap Fixed Clevis

Style BB with No Feedback



Cap Spherical Bearing

Style SB with No Feedback



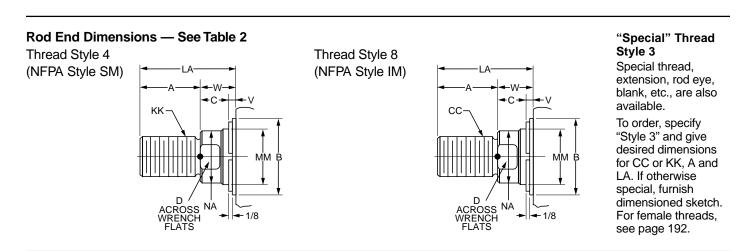


Table 1 — Envelope and Mounting Dimensions

		SAE	EE			I	н					2	ĸ					+.000					L Add S	B Stroke	s	J
Bore	Е	*	**	F	G	*	**	J	к	L	М	*	**	LR	MR	СВ	CW	CD [†]	EX	MA	MS	NR	*	**	*	**
2	3	10	NA	5/ ₈	13/4	47/8	NA	11/2	7/ ₁₆	11/4	3/4	17/8	NA	1	15/16	11/4	5/8	.751	21/32	1	13/8	1	6 ⁵ /8	81/8	27/8	NA
21/2	31/2	10	12	5/ ₈	13/4	5 ³ /8	55/8	11/2	7/ ₁₆	1 1/4	3/4	21/4	3.04	15/16	15/16	1 1/4	5/8	.751	21/32	1	13/8	1	6 ³ /4	81/4	27/8	43/8
31/4	41/2	12	12	3/4	2	65/8	65/8	11/2	9/ ₁₆	11/2	1	23/4	3.54	11/4	13/ ₁₆	11/2	3/4	1.001	7/8	11/4	1 ¹¹ / ₁₆	1 1/4	73/8	87/8	27/8	43/8
4	5	12	12	7/8	2	71/8	71/8	13/4	9/ ₁₆	21/8	13/8	31/8	3.125	13/4	15/8	2	1	1.376	1 ³ /16	17/8	27/16	15/8	91/4	91/4	43/8	43/8
5	61/2	12	12	7/8	2	85/8	85/8	13/4	13/16	21/4	13/4	35/8	3.625	21/16	21/8	21/2	11/4	1.751	117/32	21/2	27/8	21/16	9 ³ / ₄	9 ³ / ₄	43/8	43/8

†Dimension CD is pin diameter.

*For lower flow valves — see page 172, Group A, G. ** For higher flow valves — see page 172, Group D, H.

Table 2 — Rod End and Envelope Dimensions

			Thr	ead											Add S	Stroke		
	Rod	Rod Dia.				+.000 002							Х	D	Z	D	Z	H
Bore	No.	MM	CC	KK	Α	В	С	D	LA	NA	V	W	*	**	*	**	*	**
2	2	13/8	11/4-12	1-14	1 ⁵ /8	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 5/16	3/8	1	10 ³ /8	117/8	11 1/8	125/8	113/8	127/8
21/2	2	13/4	1 ¹ / ₂ -12	11/4-12	2	2.374	3/4	1 1/2	31/4	1 ¹¹ / ₁₆	1/ ₂	1 ¹ / ₄	10 ³ /4	12 ¹ / ₁₄	11 1/2	13	113/4	13 ¹ /4
Z 1/2	3	1 ³ /8	11/4-12	1-14	1 ⁵ /8	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 5/16	3/8	1	10 ¹ /2	12	11 1/4	12 ³ /4	11 ¹ / ₂	13
	1	1 ³ /8	11/4-12	1-14	1 ⁵ /8	1.999	5/ ₈	1 1/8	21/2	1 5/16	1/4	7/8	11 ¹ / ₄	12 ³ /4	121/4	13 ³ /4	121/2	14
31/4	2	2	1 ³ /4-12	1 ¹ / ₂ -12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 1/2	1 ^{15/} 16	3/8	1 1/4	11 ⁵ /8	13 ¹ /8	125/8	14 ¹ /8	127/8	14 ³ /8
	3	1 ³ /4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 1/2	31/ ₈	1 ^{11/} 16	3/8	1 1/8	11 ¹ /2	13	12 1/2	14	123/4	141/4
	1	1 ³ /4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 1/2	3	1 ^{11/} 16	1/4	1	14 ¹ /8	14 ¹ /8	151/2	151/2	16	16
4	2	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 3/8	2 ³ /8	3/8	1 ³ /8	14 ¹ /2	14 ¹ /2	157/8	157/8	16 ³ /8	16 ³ /8
	3	2	1 ³ /4-12	1 ¹ / ₂ -12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 ³ /8	1 ^{15/} 16	1/4	1 1/8	14 ¹ /4	14 ¹ /4	155/8	15 ⁵ /8	16 ¹ /8	16 ¹ /8
	1	2	1 ³ /4-12	1 ¹ / ₂ -12	2 ¹ / ₄	2.624	7/ ₈	1 ^{11/} 16	3 ³ /8	1 ^{15/} 16	1/4	1 1/8	147/8	147/ ₈	16 ⁵ /8	16 ⁵ /8	17 ³ /8	17 ³ /8
5	2	3 ¹ / ₂	31/4-12	2 ¹ / ₂ -12	3 ¹ / ₂	4.249	1	3	47/ ₈	3 ³ /8	3/8	1 ³ /8	15 ¹ /8	15 ¹ /8	16 ⁷ /8	16 ⁷ /8	175/8	175/8
3	3	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	2 ³ /8	3/8	1 ³ /8	15 ¹ /8	15 ¹ /8	16 ⁷ /8	16 ⁷ /8	175/8	175/8
	4	3	23/4-12	21/4-12	31/2	3.749	1	25/8	47/ ₈	27/8	3/8	1 ³ /8	15 ¹ /8	15 ¹ /8	16 ^{7/8}	167/8	175/8	175/8

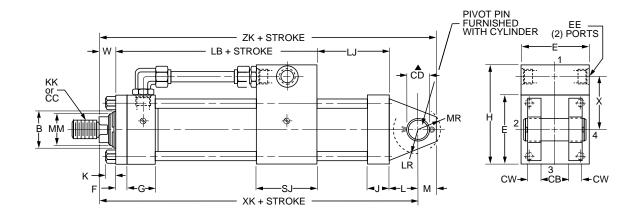
*For lower flow valves — see page 172, Group A, G. ** For higher flow valves — see page 172, Group D, H.



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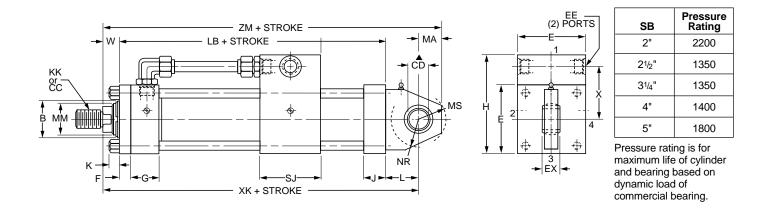
Cap Fixed Clevis

Style BB with LDT and LRT Feedback



Cap Spherical Bearing

Style SB with LDT and LRT Feedback



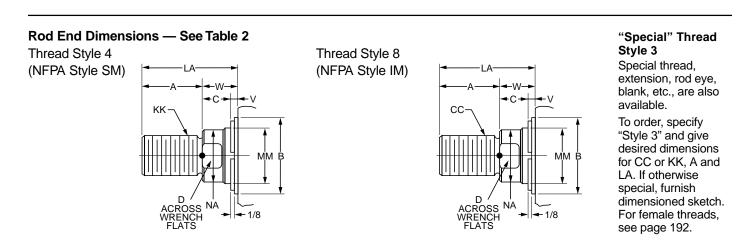


Table 1 — Envelope and Mounting Dimensions

		SAE	EE				H)	(+.000					L Add S	B Stroke	s	J	
Bore	Е	*	**	F	G	*	**	J	к	L	М	*	**	LR	MR	СВ	CW	CD [†]	EX	MA	MS	NR	*	**	*	**	LJ ^{††}
2	3	10	NA	5/ ₈	13/4	47/8	NA	1 1/2	7/ ₁₆	11/4	3/4	17/8	NA	1	15/16	1 1/4	5/ ₈	.751	21/32	1	13/8	1	65/8	NA	27/8	NA	51/2
21/2	31/2	10	12	5/ ₈	13/4	5 ³ /8	55/8	11/2	7/ ₁₆	1 1/4	3/4	21/4	3.04	15/16	15/16	1 1/4	5/ ₈	.751	21/32	1	13/8	1	6 ³ /4	81/4	27/8	43/8	51/2
31/4	41/2	12	12	3/4	2	65/8	6 ⁵ /8	11/2	9/ ₁₆	11/2	1	23/4	3.54	1 1/4	1 ^{3/} 16	11/2	3/4	1.001	7/8	1 1/4	1 ¹¹ / ₁₆	11/4	73/8	87/8	27/8	43/ ₈	51/2
4	5	12	12	7/8	2	71/8	71/8	13/4	9/ ₁₆	21/8	13/8	31/8	3.125	13/4	15/8	2	1	1.376	13/16	17/8	27/16	15/8	91/4	91/4	43/8	43/8	53/4
5	61/2	12	12	7/ ₈	2	85/8	8 ⁵ /8	13/4	13/ ₁₆	21/4	13/4	35/8	3.625	21/16	21/8	21/2	11/4	1.751	117/32	21/2	27/8	21/16	93/4	93/4	43/8	43/8	53/4

†Dimension CD is pin diameter.

*For lower flow valves — see page 172, Group A, G. ** For higher flow valves — see page 172, Group D, H.

††"RO" style integral cable only on LDT. For RB style connection on LDT consult factory for LJ, ZK, XK dimensions.

Velocity of LRT actuators must not exceed 30 ips.

			Thr	ead											Add S	Stroke		
	Rod	Rod Dia.				+.000							Х	к	Z	К	Z	М
Bore	No.	MM	СС	кк	A	B.002	С	D	LA	NA	V	w	*	**	*	**	*	**
2	2	13/ ₈	11/4-12	1-14	15/ ₈	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 ⁵ / ₁₆	3/8	1	14 ³ /8	15 ⁷ /8	15 ^{1/8}	16 ⁵ /8	15 ³ /8	167/8
21/2	2	13/4	11/2-12	11/4-12	2	2.374	3/4	1 1/2	31/4	1 ¹¹ / ₁₆	1/ ₂	1 ¹ / ₄	14 ³ /4	16 ¹ /14	151/2	17	15 ³ /4	17 ¹ / ₄
2.12	3	1 ³ /8	11/4-12	1-14	15/8	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 ^{5/} 16	3/8	1	14 ¹ /2	16	151/4	16 ³ /4	15 ¹ /2	17
	1	1 ³ /8	11/4-12	1-14	15/8	1.999	5/ ₈	1 1/8	2 ¹ / ₂	1 ⁵ / ₁₆	1/4	7/8	15 ¹ /4	16 ³ /4	16 ¹ / ₄	173/4	16 ¹ /2	18
31/4	2	2	1 ³ / ₄ -12	1 ¹ / ₂ -12	21/4	2.624	7/8	1 ¹¹ / ₁₆	3 1/2	1 ^{15/} 16	3/8	1 ¹ / ₄	15 ⁵ /8	17 ¹ /8	165/8	18 ¹ /8	16 ⁷ /8	18 ³ /8
	3	13/4	11/2-12	11/4-12	2	2.374	3/4	1 1/2	3 1/8	1 ¹¹ / ₁₆	3/8	1 ¹ / ₈	15 ¹ /2	17	16 ¹ / ₂	18	16 ³ /4	181/4
	1	13/4	1 ¹ / ₂ -12	11/4-12	2	2.374	3/4	1 ¹ / ₂	3	1 ¹¹ / ₁₆	1/4	1	18 ¹ /8	18 ¹ /8	19 1/2	19 ¹ / ₂	20	20
4	2	21/2	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	2 ³ /8	3/8	1 ³ /8	18 ¹ /2	18 ¹ /2	197/ ₈	197/8	20 ³ /8	203/8
	3	2	1 ³ / ₄ -12	1 ¹ / ₂ -12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 ³ /8	1 ^{15/} 16	1/4	1 ¹ / ₈	18 ¹ /4	18 ¹ /4	19 ^{5/8}	19 ⁵ /8	201/8	201/8
	1	2	13/4-12	1 ¹ / ₂ -12	21/4	2.624	7/ ₈	1 ¹¹ / ₁₆	3 ³ /8	1 ^{15/} 16	1/4	1 ¹ / ₈	18 ⁷ /8	187/ ₈	205/8	205/8	21 ³ /8	21 ³ /8
5	2	31/2	31/4-12	2 ¹ / ₂ -12	31/2	4.249	1	3	47/ ₈	3 ³ /8	3/8	1 ³ /8	19 ¹ /8	19 ¹ /8	207/8	207/8	21 ⁵ /8	215/8
5	3	21/2	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	2 ³ /8	3/8	1 ³ /8	19 ¹ /8	19 ¹ /8	207/8	207/8	21 ⁵ /8	215/8
	4	3	23/4-12	21/4-12	31/2	3.749	1	2 ⁵ /8	47/ ₈	27/8	3/8	1 ³ /8	19 ¹ /8	19 ¹ /8	207/8	207/8	215/8	215/8

Table 2 — Rod End and Envelope Dimensions

Note: Electrical port or connector will be provided at position 1 of rear cap.

Mounting styles BB, B, SB with analog LDT feedback require the use of Analog Output Module (AOM).

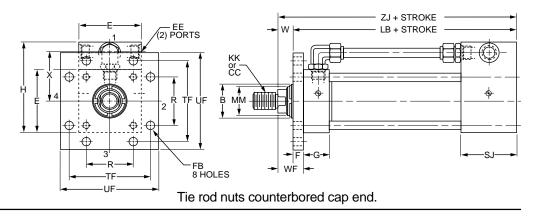
*For lower flow valves — see page 172, Group A, G. ** For higher flow valves — see page 172, Group D, H.



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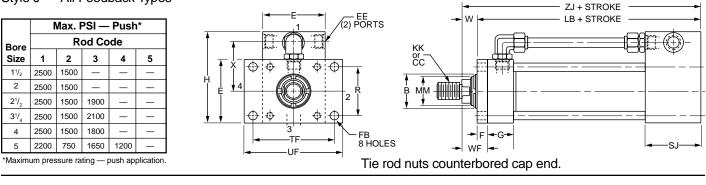
Head Square Flange

Style JB — All Feedback Types



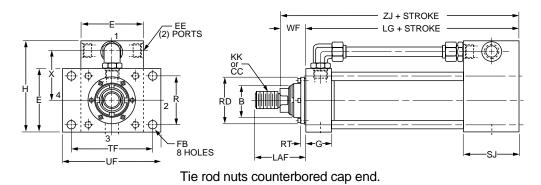
Head Rectangular Flange

Style J — All Feedback Types



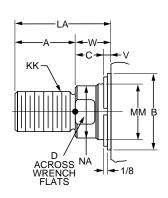
Head Rectangular

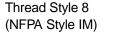
Style JJ — All Feedback Types

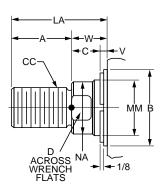


Rod End Dimensions — See Table 2

Thread Style 4 (NFPA Style SM)







"Special" Thread Style 3

Special thread, extension, rod eye, blank, etc., are also available.

To order, specify "Style 3" and give desired dimensions for CC or KK, A and LA. If otherwise special, furnish dimensioned sketch. For female threads, see page 192.

Table 1 — Envelope and Mounting Dimensions

		SAE	EE			ŀ	4)	ĸ				L Add S	B Stroke	L Add S	G Stroke	s	J
Bore	E	*	**	F	G	*	**	к	R	*	**	FB	TF	UF	*	**	*	**	*	**
2	3	10	NA	5/ ₈	13/4	47/8	NA	7/ ₁₆	2.05	17/8	NA	9/ ₁₆	41/ ₈	51/ ₈	65/8	NA	6	NA	27/8	NA
21/2	31/2	10	12	5/ ₈	13/4	5 ³ /8	55/8	7/ ₁₆	2.55	21/4	3.04	9/ ₁₆	45/ ₈	5 ⁵ /8	63/4	81/4	6 ¹ /8	75/8	27/8	43/8
31/4	41/2	12	12	3/4	2	6 ⁵ /8	6 ⁵ /8	9/ ₁₆	3.25	23/4	3.54	11/16	57/ ₈	71/8	73/8	87/ ₈	65/8	81/ ₈	27/8	43/ ₈
4	5	12	12	7/8	2	71/8	71/8	9/16	3.82	31/8	3.125	11/16	6 ³ /8	75/ ₈	91/4	91/4	8 3/8	83/ ₈	43/8	43/8
5	61/2	12	12	7/8	2	85/8	85/8	13/ ₁₆	4.95	35/8	3.625	^{5/} 16	8 ³ / ₁₆	9 ³ / ₄	9 ³ / ₄	9 ³ /4	87/4	87/8	43/8	43/8

*For lower flow valves — see page 172, Group A, G. **For higher flow valves — see page 172, Group D, H. Velocity of LRT actuators must not exceed 30 ips.

			Thr	ead													7	. 1
Bore	Rod No.	Rod Dia. MM	сс	кк	A	+.000 002 B	с	D	LA	LAF	NA	V	w	Max. RD	RT	WF	Add 3	:J Stroke **
2	2	13/8	11/4-12	1-14	15/ ₈	1.999	5/ ₈	1 1/8	2 ⁵ /8	31/4	1 ^{5/} 16	3/8	1	3	3/8	15/8	7 5/8	91/ ₈
01/	2	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 ¹ / ₂	31/4	37/8	1 ¹¹ / ₁₆	1/ ₂	1 ¹ / ₄	3 ¹ /2	3/8	17/8	8	91/ ₂
21/2	3	1 ³ /8	11/4-12	1-14	15/8	1.999	5/ ₈	1 1/8	2 ⁵ /8	31/4	1 5/ ₁₆	3/8	1	3	3/8	15/8	73/4	91/4
	1	1 ³ /8	11/4-12	1-14	15/8	1.999	5/ ₈	1 1/8	2 ¹ / ₂	31/4	1 5/16	1/4	7/8	3	3/8	15/8	81/4	9 3/4
31/4	2	2	1 ³ /4-12	1 ¹ /2-12	2 ¹ / ₄	2.624	7/ ₈	1 ¹¹ / ₁₆	3 1/2	4 1/ ₄	1 ^{15/} 16	3/8	1 1/4	4	5/ ₈	2	8 5/8	101/8
	3	1 ³ /4	1 ¹ /2-12	1 ¹ /4-12	2	2.374	3/4	1 ¹ / ₂	31/8	37/8	1 ¹¹ / ₁₆	3/8	1 1/8	3 ¹ / ₂	3/8	17/8	81/2	10
	1	13/4	1 ¹ / ₂ -12	11/4-12	2	2.374	3/4	1 ¹ / ₂	3	37/8	1 ^{11/} 16	1/4	1	3 ¹ / ₂	3/8	17/8	101/4	101/4
4	2	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	51/4	2 ³ /8	3/8	1 ³ /8	4 ¹ /2	5/ ₈	2 ¹ / ₄	105/8	105/8
	3	2	1 ³ /4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ¹¹ / ₁₆	3 ³ /8	4 1/ ₄	1 ^{15/} 16	1/4	1 1/8	4	5/ ₈	2	10 ³ /8	103/8
	1	2	1 ³ /4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ¹¹ / ₁₆	3 ³ /8	4 1/ ₄	1 ^{15/} 16	1/4	1 1/8	4	5/ ₈	2	97/ ₈	107/8
5	2	3 ¹ / ₂	31/4-12	21/2-12	31/2	4.249	1	3	47/ ₈	5 ³ /4	3 ³ /8	3/8	1 ³ /8	5 ³ /4	5/ ₈	21/4	11 1/8	11 1/8
5	3	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	51/4	2 ³ /8	3/8	1 ³ /8	4 ¹ /2	5/ ₈	21/4	11 1/8	11 1/8
	4	3	2 ³ /4-12	21/4-12	31/2	3.749	1	2 ⁵ /8	47/ ₈	5 ³ /4	27/8	3/8	1 ³ /8	5 ¹ /4	5/8	21/4	11 1/8	11 1/8

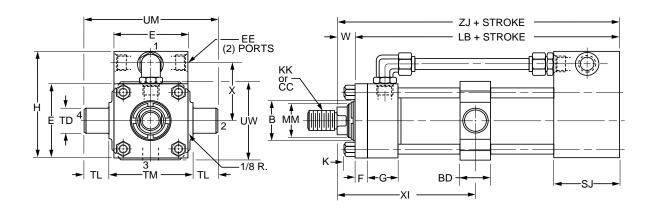
*For lower flow valves — see page 172, Group A, G. **For higher flow valves — see page 172, Group D, H.



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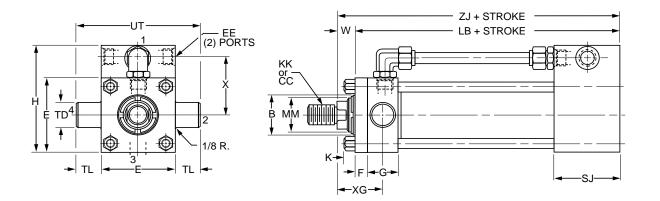
Intermediate Trunnion

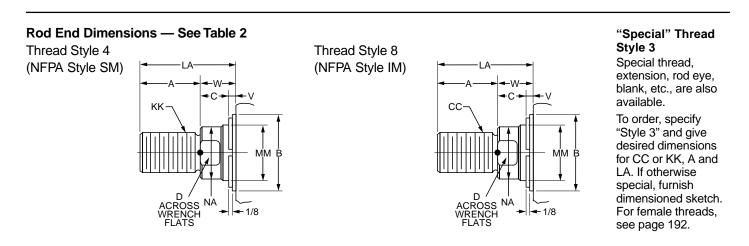
Style DD — All Feedback Types



Head Trunnion

Style D — All Feedback Types





			SAE	EEE			ŀ	ł		2	x	+.000						L Add S	B Stroke	s	5J
Bore	BD	Е	*	**	F	G	*	**	κ	*	**	TD	TL	тм	UW	UM	UT	*	**	*	**
2	11/2	3	10	NA	5/8	13/4	47/ ₈	NA	7/ ₁₆	17/8	NA	1.375	13/8	31/2	41/8	61/4	53/4	6 ⁵ /8	NA	27/8	NA
21/2	11/2	31/2	10	12	5/8	13/4	5 ³ /8	55/8	7/ ₁₆	21/4	3.04	1.375	13/8	4	45/8	6 ³ /4	61/4	6 ³ / ₄	81/4	27/8	43/8
31/4	2	41/2	12	12	3/4	2	65/8	6 ⁵ /8	^{9/} 16	23/4	3.54	1.750	13/4	5	5 ^{13/} 16	81/2	8	73/8	87/ ₈	27/8	43/8
4	2	5	12	12	5/8	2	71/8	71/8	^{9/} 16	31/8	3.125	1.750	13/4	51/2	6 ³ /8	9	81/2	91/4	91⁄4	43/8	43/8
5	2	61/2	12	12	7/8	2	85/8	85/9	13/16	35/8	3 625	1 750	13/4	7	73/4	101/2	10	93/4	93/4	43/2	43/2

*For lower flow valves — see page 172, Group A, G. ** For higher flow valves — see page 172, Group D, H. Velocity of LRT actuators must not exceed 30 ips.

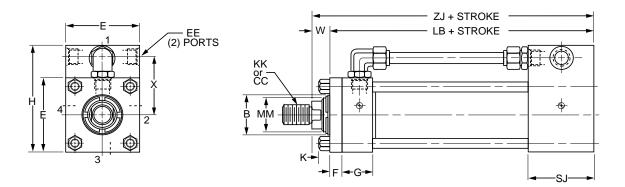
			Thr	ead											Z	ZJ
	Rod	Rod Dia.				+.000 002								Min.		Stroke
Bore	No.	MM	сс	кк	А	B	С	D	LA	NA	V	W	XG	XI†	*	**
2	2	13/ ₈	11/4-12	1-14	1 ⁵ /8	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 ⁵ / ₁₆	3/8	1	2 ¹ / ₂	4 ³ / ₁₆	75/ ₈	91/ ₈
21/2	2	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 1/2	31/4	1 ¹¹ / ₁₆	1/2	1 1/4	2 ³ /4	47/ ₁₆	8	91/ ₂
Z 1/2	3	1 ³ /8	11/4-12	1-14	1 ⁵ /8	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 5/16	3/8	1	2 ¹ /2	4 ³ / ₁₆	73/4	91/4
	1	1 ³ /8	11/4-12	1-14	1 ⁵ /8	1.999	5/ ₈	1 1/8	2 ¹ / ₂	1 5/16	1/4	7/8	2 ⁵ /8	411/16	81/4	93/4
31/4	2	2	13/4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 1/2	1 ^{15/} 16	3/8	1 1/4	3	5 ¹ /16	8 5/8	101/8
	3	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 1/2	3 ¹ /8	1 ¹¹ / ₁₆	3/8	1 1/8	27/8	4 ¹⁵ / ₁₆	81/2	10
	1	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 1/2	3	1 ¹¹ / ₁₆	1/4	1	27/8	4 ¹⁵ / ₁₆	101/4	101/4
4	2	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	2 ³ /8	3/8	1 ³ /8	31/4	5 ^{5/} 16	105/8	10 ⁵ /8
	3	2	13/4-12	1 ¹ / ₂ -12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 ³ / ₈	1 ^{15/} 16	1/4	1 1/8	3	5 ¹ / ₁₆	10 ³ /8	10 ³ /8
	1	2	13/4-12	1 ¹ / ₂ -12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 ³ / ₈	1 ^{15/} 16	1/4	1 1/8	3	5 ¹ / ₁₆	97/ ₈	107/8
5	2	31/2	31/4-12	2 ¹ / ₂ -12	3 1/2	4.249	1	3	47/ ₈	3 ³ /8	3/8	1 ³ /8	3 ¹ /4	5 ⁵ /16	11 1/8	11 1/8
5	3	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	2 ³ /8	3/8	1 ³ /8	3 ¹ /4	5 ⁵ /16	11 1/8	11 1/8
	4	3	23/4-12	21/4-12	31/ ₂	3.749	1	2 ⁵ /8	47/ ₈	27/8	3/8	1 ³ /8	31/4	5 ⁵ /16	11 1/8	11 1/8

†Dimension XI to be specified by customer. *For lower flow valves — see page 172, Group A, G. ** For higher flow valves — see page 172, Group D, H.



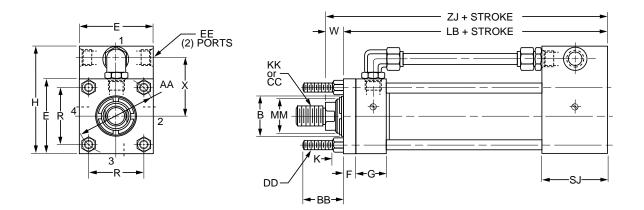
No Mount

Style T — All Feedback Types



Tie Rods Extended Head End

Style TB — All Feedback Types



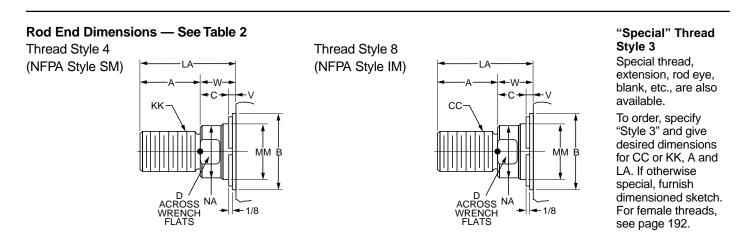


Table 1 — Envelope and Mounting Dimensions

					SAE	EE			I	4			3	x	L Add S	B Stroke	s	IJ
Bore	AA	BB	DD	Е	*	**	F	G	*	**	к	R	*	**	*	**	*	**
2	2.90	1 ¹³ / ₁₆	1/2-20	3	10	NA	5/ ₈	13/4	47/8	NA	7/ ₁₆	2.05	17/8	NA	65/8	NA	27/8	NA
21/2	3.60	1 13/ ₁₆	1/2-20	31/2	10	12	5/ ₈	13/4	5 ³ /8	5 ⁵ /8	7/ ₁₆	2.55	21/4	3.04	63/4	81/4	27/8	43/8
31/4	4.60	2 ^{5/} 16	⁵ /8-18	41/2	12	12	3/4	2	6 ⁵ /8	6 ⁵ /8	9/ ₁₆	3.25	23/4	3.54	7 ³ /8	87/ ₈	27/8	4 ³ / ₈
4	5.40	2 ⁵ / ₁₆	⁵ /8-18	5	12	12	7/8	2	71/8	71/8	9/ ₁₆	3.82	31/8	3.125	91/4	91/4	43/8	43/8
5	7.00	3 ³ /16	7/8-14	61/2	12	12	7/8	2	85/8	85/8	13/16	4.95	35/8	3.625	9 ³ / ₄	9 ³ / ₄	43/8	43/8

*For lower flow valves — see page 172, Group A, G. **For higher flow valves — see page 172, Group D, H. Velocity of LRT actuators must not exceed 30 ips.

				-										
			Thr	ead									7	J
	Rod	Rod Dia.				+.000 002								Stroke
Bore	No.	MM	cc	кк	А	002 B	С	D	LA	NA	V	w	*	**
2	2	13/ ₈	11/4-12	1-14	15/ ₈	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 ^{5/} 16	3/8	1	7 5/8	91/ ₈
21/2	2	13/4	1 ¹ / ₂ -12	11/4-12	2	2.374	3/4	1 1/2	31/4	1 ¹¹ / ₁₆	1/ ₂	1 ¹ / ₄	8	91/ ₂
∠ 1/2	3	1 ³ /8	11/4-12	1-14	15/8	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 5/ ₁₆	3/8	1	73/4	91/4
	1	1 ³ /8	11/4-12	1-14	15/ ₈	1.999	5/ ₈	1 1/8	2 ¹ / ₂	1 ^{5/} 16	1/4	7/8	81/4	93/4
31/4	2	2	13/4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 1/2	1 ^{15/} 16	3/8	1 ¹ / ₄	8 5/8	101/8
	3	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 ¹ / ₂	3 1/8	1 ¹¹ / ₁₆	3/8	1 1/8	8 1/2	10
	1	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 ¹ / ₂	3	1 ¹¹ / ₁₆	1/4	1	101/4	101/4
4	2	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	21/16	4 ³ / ₈	23/8	3/8	1 ³ /8	105/8	105/8
	3	2	13/4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 ³ / ₈	1 ^{15/} 16	1/4	1 1/8	103/8	10 ³ /8
	1	2	13/4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 ³ / ₈	1 ^{15/} 16	1/4	1 1/8	97/ ₈	107/8
5	2	31/2	31/4-12	2 ¹ / ₂ -12	31/2	4.249	1	3	47/ ₈	3 ³ /8	3/8	1 ³ /8	11 1/8	11 1/8
5	3	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ /8	23/8	3/8	1 ³ /8	11 1/8	11 1/8
	4	3	23/4-12	21/4-12	31/2	3.749	1	2 ⁵ /8	47/ ₈	27/8	3/8	1 ³ /8	11 1/8	11 1/8

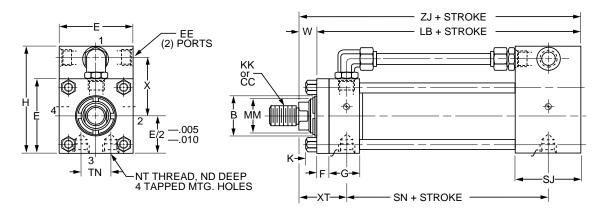
*For lower flow valves — see page 172, Group A, G.

**For higher flow valves — see page 172, Group D, H.



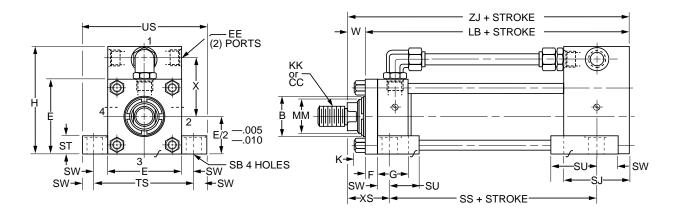
Side Tapped

Style F — All Feedback Types



Side Lugs

Style C — All Feedback Types



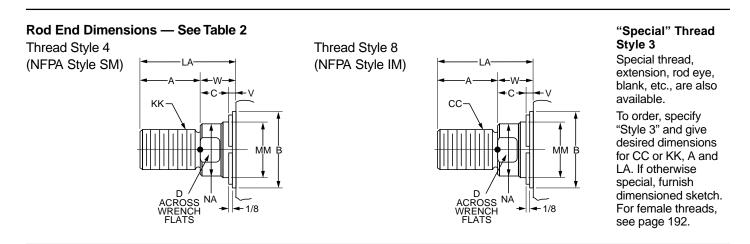


Table 1 — Envelope and Mounting Dimensions

		SAE	EE			ł	H			2	ĸ									L Add S	.B Stroke	s	J	Add S	Stroke
Bore	Е	*	**	F	G	*	**	J	к	*	**	NT	SB [†]	ST	SU	SW	ΤN	тs	US	*	**	**	*	SS	SN
2	3	10	NA	5/8	13/4	47/8	NA	11/2	7/ ₁₆	17/8	NA	1/2-13	^{9/} 16	3/4	1 1/4	1/2	15/ ₁₆	4	5	65/8	NA	27/8	NA	35/8	27/8
21/2	31/2	10	12	5/ ₈	13/4	5 ³ /8	55/8	11/2	7/ ₁₆	21/4	3.04	⁵ /8-11	13/ ₁₆	1	1º/16	11/16	15/16	47/8	61/4	63/4	81/4	27/8	43/8	33/8	3
31/4	41/2	12	12	3/4	2	6 ⁵ /8	6 ⁵ /8	11/2	9/ ₁₆	23/4	3.54	³ / ₄ -10	^{13/} 16	1	1º/ ₁₆	¹¹ / ₁₆	1 ½	57/ ₈	71/4	7 ³ /8	87/ ₈	27/8	43/ ₈	41/ ₈	31/2
4	5	12	12	7/ ₈	2	7 1/8	71/8	13/4	9/ ₁₆	31/8	3.125	1-8	1 1/16	1 1/4	2	7/8	21/16	63/4	81/2	91/4	91/4	43/8	43/8	4	33/4
5	61/2	12	12	7/8	2	85/8	8 ⁵ /8	13/4	13/16	35/8	3.625	1-8	1 ¹ /16	11/4	2	7/8	2 ^{15/} 16	81/4	10	9 ³ / ₄	93/4	43/8	43/8	41/2	41/4

*For lower flow valves — see page 172, Group A, G. **For higher flow valves — see page 172, Group D, H. Velocity of LRT actuators must not exceed 30 ips. †Upper surface spot faced for socket head screws.

Table 2 — Rod End and Envelope Dimensions

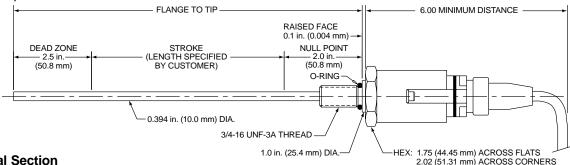
			Thr	bee													
	Rod	Rod Dia.	Style 8	Style 4 & 9		+.000											<u>ZJ</u> Stroke
Bore	No.	MM	cc	KK	А	B	С	D	LA	NA	V	W	ND	XS	ΧТ	*	*
2	2	13/ ₈	11/4-12	1-14	15/ ₈	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 5/ ₁₆	3/8	1	⁷ /16	21/8	25/ ₈	7 5/8	91/ ₈
21/ ₂	2	13/4	1 ¹ / ₂ -12	11/4-12	2	2.374	3/4	1 1/2	31/4	1 ¹¹ / ₁₆	1/2	1 ¹ / ₄	1/ ₂	2 ⁹ / ₁₆	27/8	8	91/2
∠ 1/2	3	1 ³ /8	11/4-12	1-14	15/8	1.999	5/ ₈	1 1/8	2 ⁵ /8	1 ^{5/} 16	3/8	1	1/2	2 ⁵ /16	25/8	73/4	91/4
	1	1 ³ /8	11/4-12	1-14	15/8	1.999	5/ ₈	1 1/8	2 ¹ / ₂	1 ^{5/} 16	1/4	7/8	11/16	2 ⁵ /16	23/4	81/4	93/4
31/4	2	2	13/4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 1/2	1 ^{15/} 16	3/8	1 1/4	^{11/} 16	211/16	3 1/8	85/8	101/8
	3	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 1/2	3 1/8	1 ¹¹ / ₁₆	3/8	1 1/8	^{11/} 16	2 ^{9/} 16	3	81/2	10
	1	13/4	1 ¹ /2-12	11/4-12	2	2.374	3/4	1 1/2	3	1 ¹¹ / ₁₆	1/4	1	^{11/} 16	23/4	3	101/4	101/4
4	2	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ / ₈	2 ³ /8	3/8	1 ³ /8	^{11/} 16	31/8	3 3/8	105/8	105/8
	3	2	13/4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 ³ /8	1 ^{15/} 16	1/4	1 1/8	^{11/} 16	27/8	3 1/8	103/8	103/8
	1	2	13/4-12	1 ¹ /2-12	21/4	2.624	7/ ₈	1 ^{11/} 16	3 3/8	1 ^{15/} 16	1/4	1 1/8	1	27/8	3 1/8	97/ ₈	107/8
5	2	3 ¹ / ₂	31/4-12	21/2-12	31/2	4.249	1	3	47/ ₈	3 ³ /8	3/8	1 ³ /8	1	31/8	3 3/8	11 1/8	11 1/8
3	3	2 ¹ / ₂	21/4-12	1 ⁷ /8-12	3	3.124	1	2 ¹ / ₁₆	4 ³ / ₈	2 ³ /8	3/8	1 ³ /8	1	31/8	3 3/8	11 1/8	11 1/8
	4	3	2 ³ / ₄ -12	21/4-12	31/2	3.749	1	25/8	47/ ₈	27/8	3/8	1 ³ /8	1	31/8	33/8	111/8	111/8

*For lower flow valves — see page 172, Group A, G. **For higher flow valves — see page 172, Group D, H.



Transducer

LDT Technical Specifications



LDT Technical Section

The 2HX-LDT Actuator is the most versatile actuator that we offer. Utilizing the Temposonics LH[™] feedback device, there are three distinct outputs available to suit most applications. Velocity is limited primarily by the limits of mechanical components outside of the actuator, although position

Magnetostriction

In a LDT position sensor, a pulse is induced in a speciallydesigned magnetostrictive waveguide by the momentary interaction of two magnetic fields. One field comes from a movable magnet which passes along the outside of the sensor tube, the other field comes from a current pulse or interrogation pulse launched along the waveguide. The interaction between the two magnetic fields produces a strain pulse, which travels at sonic speed along the waveguide until the pulse is detected at the head of the sensor. The position of the magnet is determined with high precision by measuring the elapsed time between the launching of the electronic interrogation pulse and the arrival of the strain pulse. As a result, accurate non-contact position sensing is achieved with absolutely no wear to the sensing components.

PULSES	Π		[
LAUNCHED	l ⊲ _td_⊳		n	٥		
PULSES	Л		Л	Л		
RECEIVED			√R	EF VOLTA	٩GE	
PULSE TRAIN -] [
AVERAGE	DC)				
DC OUTPUT 0-						

Feedback Accuracy

The accuracy of a given feedback device is a composite of a number of factors, the most important of which are:

Resolution – The smallest movement of the device that will produce a measurable output.

Non-Linearity – The deviation of the signal from a straight line output.

Repeatability – The maximum deviation of output signal for repeated positioning to a fixed point.

Hysteresis – The deviation of the signal when approaching a fixed point from opposite directions.

update time can affect the system ramp-down. The 2HX-LDT Actuator is the industry favorite in tough, rugged machinery applications. A key advantage is the absolute position output which is not lost if there is a power failure.

An average of 200 ultrasonic strain pulses are launched for every reading. With so many readings taken for each position, vibration and shock have negligible effect on the readings. The transducer assembly is shielded to eliminate interference caused by electromagnetic fields in the radio frequency range. In addition, static magnetic fields of several hundred gauss must get as close as ³/₁₆" from the protective tube before any interference in transducer operation occurs.

Features

- High immunity to shock and vibration
- Replaceable sensing element
- Single voltage input +13 to 26.4Vdc
- 3000 psi operating pressure
- Multiple outputs from on-board electronics
- Easy installation and maintenance
- Standard strokes up to 78" (analog), 120" (digital)
- Includes 5' extension cable with RB connector standard

If cylinder includes false stage enclosure, LDT will be supplied with RO Integral Pigtail Cable (5' length). Refer to pages 176 and 177 for "LJ" and "E" dimensions.

Temperature Coefficient – The shift in output due to temperature change. This is a combination of the effect of temperature on the cylinder, the transducer and the electronics.

These factors which are normally additive refer to the feedback device itself. The performance achieved by a given system depends on the various factors such as system stiffness, valve performance, friction, temperature variation, and backlash in mechanical linkages to the cylinder.

In the case of front flange mounted cylinders, the stretch of the cylinder due to hydraulic pressure changes may affect position repeatability and system performance.

Standard Specifications

Parameter	Specification
Resolution:	<i>Analog:</i> Infinite <i>Digital:</i> 1 ÷ [gradient x crystal freq. (mHz) x circulation]
Non-Linearity:	±0.02% or ±0.05 mm (±0.002 in.), whichever is greater 0.002 in. is the minimum absolute linearity and varies with sensor model
Repeatability:	Equal to resolution
Hysteresis:	<0.02 mm (0.0008 in.)
Outputs:	Analog: Voltage or Current Digital: Start/Stop or PWM
Measuring Range:	<i>Analog:</i> 25 to 2000 mm (1 to 78 in.) <i>Digital:</i> 25 to 7600 mm (1 to 300 in.)
Operating Voltage:	+13.5 to 26.4 Vdc (±0%): Strokes ≤1525 mm (60 in.) +24 Vdc (±10%): Strokes > 1525 mm (60 in.)
Power Consumption:	100 mA
Operating Temperature:	Head Electronics: -40 to 70°C (-40 to 158°F) Sensing Element: -40 to 105°C (-40 to 221°F)

LDT Output Options

The LDT utilizes on-board electronics contained in the sensor head to generate several absolute output options. The required output must be specified at the time of order. In applications where it is desirable to locate the output electronics in a remote location, or where the sensor head is not accessible, an optional Analog Output Module (AOM) is available. The standard outputs for each option are listed below.

Standard LDT Outputs

Analog Position (absolute)
0 to +10V DC or +10 to 0V DC
4 to 20mA or 20 to 4mA (grounded)
0 to 20mA or 20 to 0mA (grounded)

Analog Output Module: AOM Option

The Analog Output Module provides an absolute analog displacement or optional velocity output signal. It contains the electronics to send the interrogation pulse to the LDT and receive the return pulse from the LDT. The AOM is mounted separately from the LDT and comes standard with strain relief connectors. Optional MS connectors are available.

Note: An LDT with Neuter output is required for use with an AOM. AOM is recommended to allow adjustment for cap mounting styles B, BB and SB.

Optional metal MS connectors are only available for connection to the AOM. The connection at the probe requires an MS-style connector. For applications requiring true MS connectors at the probe, consult factory.

LDT Specifications Output Options Analog Output Module

EMC Test*:	DIN EN 50081-1 (Emissions); DIN EN 50082-2 (Immunity)
Shock Rating:	100 g (single hit)/IEC standard 68-2-27 (survivability)
Vibration Rating:	5 g/10-150 Hz/IEC standard 68-2-6
Adjustability: (for active sensors only)	Field adjustable zero and span to 5% of active stroke
Update Time:	Analog: ≤1 ms Digital: Minimum = [Stroke (specified in inches) + 3] x 9.1 μs
Operating Pressure:	5000 psi static; 10,000 psi spike
Housing Style/ Enclosure:	Aluminum die-cast head, IP 67 stainless steel rod & flange (LH flange: M18 x 1.5 or 3/4-16 UNF-3A)

*EMC test specification does not include sensors with the RB connection style.

The above specifications for analog sensors are assuming that output ripple is averaged by the measuring device as with any typical analog device. Specifications are subject to change without notice. Consult the factory for specifications critical to your needs.

Note: LDT comes standard with an RB style connector and 5' extension cable. If cylinder includes style A protective enclosure, LDT will be supplied with RO Integral Pigtail Cable (5' length). Refer to pages 176 and 177 for "LJ" and "E" dimensions.

Note: Velocity output or velocity and position output requires use of an AOM.

- Digital Position (absolute) Differential Start/Stop PWM Pulse Duration
- Neuter (For use with AOM) Single Pulse Square Wave

Note: Velocity output or velocity and position output requires use of an AOM.

AOM Output Specifications

Displacement Outputs:

Voltage

- 0 to 10V DC forward and reverse acting (forward standard)
- 0 to -10V DC forward and reverse acting
- -10 to +10V DC forward and reverse acting
- 0 to +5V DC forward and reverse acting
- -5 to +5V DC forward and reverse acting **Current**
- 4 to 20 mA grounded (forward and reverse) 4 to 20 mA ungrounded (forward and reverse)

Velocity Outputs:

inches/second = $\pm 10V$ DC (1 to 400 in/sec)

Power Supply:

+24V DC standard ±15V DC optional



LDT Connector Options

The LDT is available with three standard Connector Options as shown below. The style RB connector with a 5' extension cable is standard except for BB and SB mounting styles.

RO style connector is standard for BB and SB mounting styles with a false stage enclosure. Please specify the connector option at the time of order.

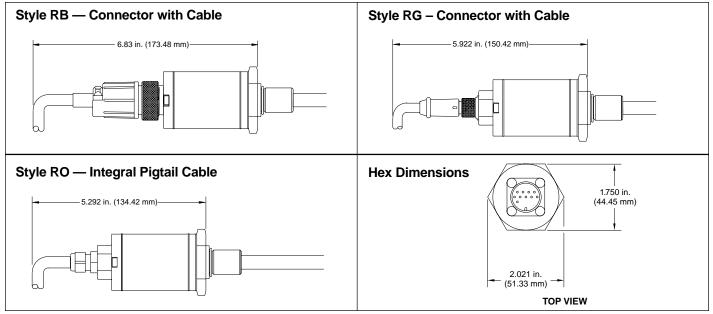


Table A — LDT Wiring with RB* Style Connector and Cable

For Temposo	onics LH™	Pulse-Duration Output (External Interrogation)	Pulse-Duration Output (Internal Interrogation)	Start/Stop Output	Neuter Output	Analog (Voltage o	
	Wire Color						
Pin No.	Solid Leads (Note 2)	Function	Function	Function	Function	Function	Function
1	White	DC Ground	DC Ground	DC Ground	DC Ground	DC Ground	DC Ground
2	Brown	Frame Ground	Frame Ground	Frame Ground	Frame Ground	Frame Ground	Frame Ground
3	Gray	(-) Gate	(-) Gate	(-) Gate	_	0 - 10 Vdc Return	Current Return
4	Pink	(+) Gate	(+) Gate	(+) Gate	_	0 to 10 Vdc	4 to 20 mA or
							0 to 20 mA or
							20 to 4mA or
							20 to 0 mA
							(See Figure A-1)
5	Red	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc
6	Blue	—	—	—	—	—	—
7	Black	—	—	—	Signal Return	10 to 0 Vdc	—
8	Violet	—	—	_	Signal Output	10 - 0 Vdc Return	—
9	Yellow	(+) Interrogation (Note 4)	—	(+) Interrogation	(+) Interrogation		—
					(Note 3)		
10	Green	(-) Interrogation (Note 4)	—	(-) Interrogation	(+) Interrogation	—	—
					(Note 3)		

Notes for Table A:

1. Interrogation pulse: 1 to 4 microseconds maximum pulse duration

2. **WARNING:** For single-ended interrogation, the unused interrogation lead must be connected to DC ground.

3. When using a Temposonics LH™ position sensor with a pulse-width-modulated output (w/external interrogation) or Start/Stop output, it is recommended that both the positiive and negative

interrogations leads are connected to a differentiated driving source to produce a differential interrogation signal.

4. **Important:** Frame ground should always be connected. When using MT, M, FT or F extension cables frame ground is the BROWN wire.

* RB style connectors are supplied as standard on all LDT's unless

specified otherwise



Figure A-1 — LDT Pin Diagram

Table B: LDT Wiring with Integral Pigtail Cable*

	Pulse-Duration Output (External Interrogation)	Pulse-Duration Output (Internal Interrogation)	Start/Stop Output	Neuter Output		Output r Current)
Integral Cable Color Code	Function	Function	Function	Function	Function (Voltage)	Function (Current)
White	DC Ground	DC Ground	DC Ground	DC Ground	DC Ground	DC Ground
Drain Wire	Frame Ground	Frame Ground	Frame Ground	Frame Ground	Frame Ground	Frame Ground
Gray	(-) Gate	(-) Gate	(-) Gate	Signal Return	0 - 10 Vdc Return	4 to 20 mA Out
Pink	(+) Gate	(+) Gate	(+) Gate	Signal Output	0 to 10 Vdc	Return (See Figure B-1)
Red	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc	+13.5 to 26.4 Vdc
Yellow	(+) Interrogation (Note 3)	_	(+) Interrogation (Note 3)	(+) Interrogation (Note 2)	10 to 0 Vdc	
Green	(-) Interrogation (Note 3)	_	(-) Interrogation (Note 3)	(-) Interrogation (Note 2)	10 - 0 Vdc Return	

Notes for Table A:

2. Warning: For single-ended intercogation, the unused interrogation lead must be connected to DC ground. 3. When replacing a Temposonics II™ position sensor with a pulse-duration output (with external interrogation) or a Start/Stop output, it is recommended that both the positive and negative interrogation leads are connected to a differentiated driving source to

produce a differential interrogation signal. Important: Frame ground should always be connected.

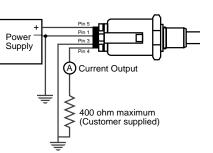


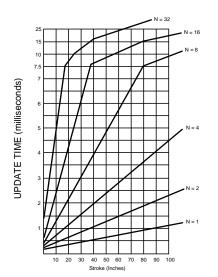
Figure B-1 -LDT with Current Output

Note: Style RO Integral Pigtail Cables are supplied as standard on LDTs used with styles A and F protective enclosures.

Digital Output Signal (PWM)

The Digital Output Electronics mounted in the head of the LDT provides the interrogation pulse to the probe. The pulse is reflected to the Digital Output Electronics by the magnet which strokes along the length of the transducer.

Figure 1. Update time (ms) = [(4.5 + stroke) inches x 0.01086 ms] x N



The LDT with PWM Digital Output provides a 5 Vdc TTL compatible pulse with modulated square wave signal which can be transmitted to a digital counter card, Parker PMC Motion Controller, or various other customer supplied devices. The amount of time, in milliseconds, that the output is "Hi," or near 5 volts, is directly proportional to the position of the cylinder piston. This time can also be called the "width" of the square wave in milliseconds. Besides being proportional to the position of the cylinder piston, this width can be controlled by varying the signal sampling rate (called "recirculations"). The advantage of increasing the recirculations is in improved resolution. The sacrifice is in update time and maximum stroke length. Figure 1 shows the relationship of recirculations, minimum update time, and stroke length. Figure 2 shows the relationship of recirculations, resolution, and stroke.

We recommend the TTL interface for most LDT applications requiring digital feedback; many electronic controllers are equipped to utilize this output. BCD and natural binary outputs are available - consult factory.

Figure 2 -**Recirculations, Resolutions and Stroke Length**

Те	rm Base	= 28 Mega	ahertz Clo	ock	
Recirculations	1	2	4	8	15
Resolution					
(inches/pulse)	0.004	0.002	0.001	0.0005	0.00035
Maximum stroke					
(inches)	258	127	61	28	12

For Cylinder Division Plant Locations - See Page II.



В

[.] Interrogation pulse: 1 to 4 microseconds maximum pulse duration.

Parker Series 2HX with LDT and Analog Output Module (AOM)

Wiring Connections and Analog Output Module Dimensions

An electrical Noise Filter and Low Ripple Output Filter are standard.

Analog Output Module

Shown with strain relief cable connectors.

Refer to Installation Bulletin 1170-TSD-2 for more detailed wiring information.

Terminal Block Connections

Terminal Block 1 — Output Signal Connections

- TB1-A Displacement Output (+)
- TB1-B Displacement Output (-)
- TB1-C Velocity (+) (Optional)
- TB1-D Velocity (-) (Optional)
- TB1-E Reserved for Options
- TB1-F Reserved for Options
- TB1-G Reserved for Options

Note: For the optional pin assignments refer to the label inside the module.

Terminal Block 2 — Transducer Connections (LDT with Neuter Output)

Terminal	Pre-1995 Cable Colors	1995 Cable Colors	Function
TB2-B	White/Blue Stripe	White	DC Ground
	Blue/White Stripe	Brown	Frame
	White/Brown Stripe	Black	Return
	Gray/White Stripe	Green	DC Ground
TB2-C	Brown/White Stripe	Violet	Return Pulse Output
TB2-E	White/Gray Stripe	Yellow	Interrogation Pulse
TB2-F	White/Green Stripe	Red	VCC (12 Vdc)

Note: Cable must be grounded at or near AOM. Note: The Transducer is supplied with a pre-wired cable.

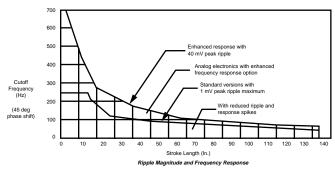
Terminal Block 3 — Power Supply Connections

TB3-H +15 Vdc TB3-J -15 Vdc TB3-K DC Common

Frequency Response

Analog Systems

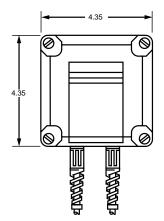
The analog output module produces a DC output signal with an AC ripple component. The group shown illustrates the following relationship between frequency response and AC ripple.

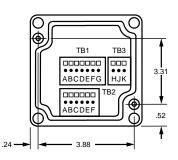


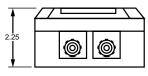
Mounting

(2) Socket Hex Cap Screws #10-32 UNF-2A Thread

Max. distance from transducer - 250 ft.







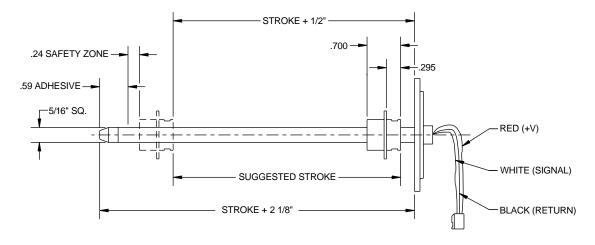
Note: AOMs require the use of an LDT with Neuter Output.

It shows that the AC ripple fundamental frequency is related to stroke length. For shorter strokes, this frequency is usually beyond the response capability of the analog control loop. Notice that the ripple frequency equals the frequency of the interrogation pulse.

It shows how the magnitude of the ripple is related to frequency response. You can enhance response by allowing the ripple to increase. Alternatively, you can use a low level of ripple, with reduced response, for applications where response is less critical, such as required for A/D converters with high resolution. Unless specified, the response will be on the 1 mV curve.

Transducer

LRT Technical Specfications

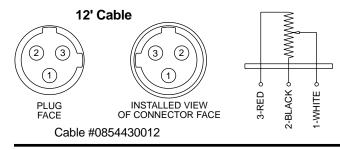


Standard Features

- Available in strokes to 120".
- Unique, easy to apply cylinder position sensing system.
- Infinite resolution, high linearity and repeatability.
- Innovative, resistive element is made of conductive plastic.
- 3 pin Brad Harrison electrical connector available at any cap position not occupied by a port or mount.

How It Works

The Parker LRT is a uniquely designed position sensor that uses a resistive element and wiper assembly to provide an analog output signal of a cylinder's position. The LRT is a dual element type linear potentiometer with two independent elements mounted on either side of an anodized aluminum extrusion. The LRT operates as a voltage divider. This is done by shorting through the extrusion with the wiper assembly. The position of the wiper changes the resistive load proportional to its position along the cylinder stroke. The LRT is energized by applying a voltage across the unit, typically 10 VDC. As the resistive load changes with the cylinder stroke, the output voltage changes proportionally. The output voltage at the end point of the cylinder stroke is dictated by the input voltage applied across the device. The probe is mounted into the cylinder cap and inserted into the gun drilled piston rod. The compactness of the design only adds to the envelope dimensions of cylinders with 1-3/4" rods and smaller. Envelope dimensions of cylinders with larger rods and integral cap style cylinders are unaffected.



Standard Specifications

Non-Linearity – Less than 0.1% of full scale up to 48" stroke. Less than 1.0% of full scale over 48" stroke.

Repeatability - .001 inch

Input Voltage - Nominal 5-50 Vdc

Operating Temperature Range - -40°F to +160°F

Cylinder Stroke Length - Up to 120"

Electrical Connector – Brad Harrison 3-pin micro connector interface at position #4 standard.

Total Resistance – 800ý per inch of stroke (±20%) + end resistance.

End Resistance - 800ý

Maximum Velocity – 30 inches per second

Life Expectancy – Greater that 50 x 10⁶ cycles (Based on 1" stroke @ 10 ips)

Fluid Medium – Petroleum based hydraulic fluids. May not be used with water based or high water content fluids.

End Voltage Loss – (V source) x (400/stroke x 800)

Power Dissipation – supply voltage squared, divided by the total resistance.

The LRT requires a high impedance interface greater than 100K ohms. A maximum of 1 microamp should be required from the LRT.

Pin Chart

Pin Number	On Cable	On LRT	Function
1	Green	White (wiper)	Ouput
2	Red w/Blk	Black (resistor base)	V-
3	Red w/White	Red (resistor tip. power)	V+

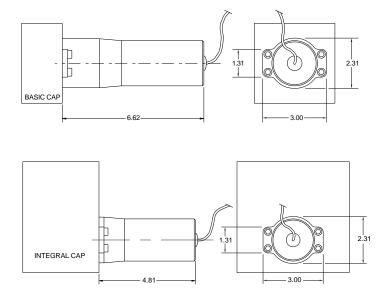
For Cylinder Division Plant Locations - See Page II.



Protective Enclosures for Feedback Devices

Style A (Not Shown) — For LDT and LRT, all bore sizes. Extra heavy-duty enclosure consisting of cylinder body tube and end cap. Consult factory for dimensions. Connector type must be specified. **Note:** Since this design uses common tie rods, the actuator must be disassembled to service or install feedback devices.

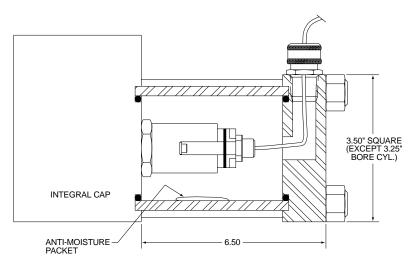
Style D — For LDT Basic and Intergral Cap. Specify connector type (not available on 2" bore).



Style F — For LDT and LRT Note: Square size is 4.5" on 3.25" bore, not available on 2" bore.

Intrinsically Safe LDT

An intrinsically safe system is a system approved by Factory Mutual as intrinsically safe for use in Class I, Division I, Group A, B, C, or D hazardous locations. The system requires approved safety barriers and a 6 wire LDT. Consult factory for detailed information.

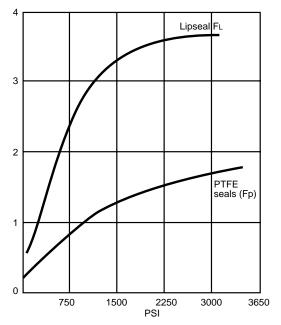


Gland Drain

Available for high speed applications is a gland drain fitted with the low friction option to prevent pressure buildup between the seals, and must be piped back to tank independent of the return line. If an independent drain line is not possible, alternative designs can be supplied.

Seal Friction

Seal friction under a given set of working conditions is not easily calculated due the multiplicity of variables involved. The following graph is offered as a guide for use in performance calculations, but for critical applications measurements should be made under simulated or actual working conditions.



Calculation of Running Friction

The seal friction attributable to the cylinder is calculated as the sum of the friction due to the individual sealing elements = (wiper seal friction + rod seal friction + piston seal friction), using the following formulae:

Seal Option:

Formula: 12d + 12F₁d + 24F₁D

12d + 12F_Ld + 12F_pD

 $12d + 30F_{p}d + 6F_{p}D$

D = bore dia. (in.)

Lipseal Rod + Piston Lipseal Rod w/ Low Friction Piston Low Friction Rod + Piston

Where: d = rod dia. (in.)

- F_{L} = friction factor for lipseals (F_{L})
- F_p = friction factor for PTFE (F_p)

Breakaway Friction

Breakaway friction may be calculated by applying the following correction factors:

Correction factors:

Lipseals:	F _L × 1.5
Low Friction:	F _p X 1.0

Sample Calculation

2HX cylinder with 3.25 dia. bore + 1.75 dia. piston rod with low friction seals at 1500 psi.

Running Friction Calculation

Friction (lbs. force) 3 12d + 3 OF_pd + 6 F_pD Friction (lbs. force) 3 12 (1.75) + 30 (1.3 x 1.75) + 6 (1.3 x 3.25) Friction (lbs. force) 3 115 Breakaway Friction Calculation

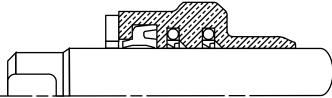
F_p X 1.0 3 F_p

Based on zero pressure:

Friction (lbs. force) 3 12d + 30F_pd + 6F_pD Friction (lbs. force) 3 12 (1.75) + 30 (1.3 × 1.75) + 6 (1.3 × 3.25) Friction (lbs. force) 3 43

Low Friction Gland

Below is a cross-sectional representation of a Parker Series 2HX low friction gland. The dual step seals are of a bronzefilled PTFE material. The expanders are a square cross section elastomer.



Operating Temperature Danger

The piston to piston-rod threaded connection is secured with an anaerobic adhesive which is temperature sensitive. Operation of the cylinder outside of the following guidelines can cause the piston rod to unthread itself from the piston. Cylinders ordered with standard seals are assembled with anaerobic adhesive with a maximum temperature rating of $+165\frac{1}{2}$ F. Cylinders ordered with Viton* seals are assembled with an anaerobic adhesive with a maximum temperature rating of $+250\frac{1}{2}$ F. When cylinders are intended for use above $+250\frac{1}{2}$ F, a pinned piston to piston-rod connection must be specified. Consult factory for details.

Consult factory for the compatibility of Viton with specific hydraulic fluids.

Fluid Compatibility

Parker Series 2HX actuators are equipped with seals and materials compatible with petroleum base hydraulic oils. For other fluids, consult factory.

How to Order Low Friction Rod Gland

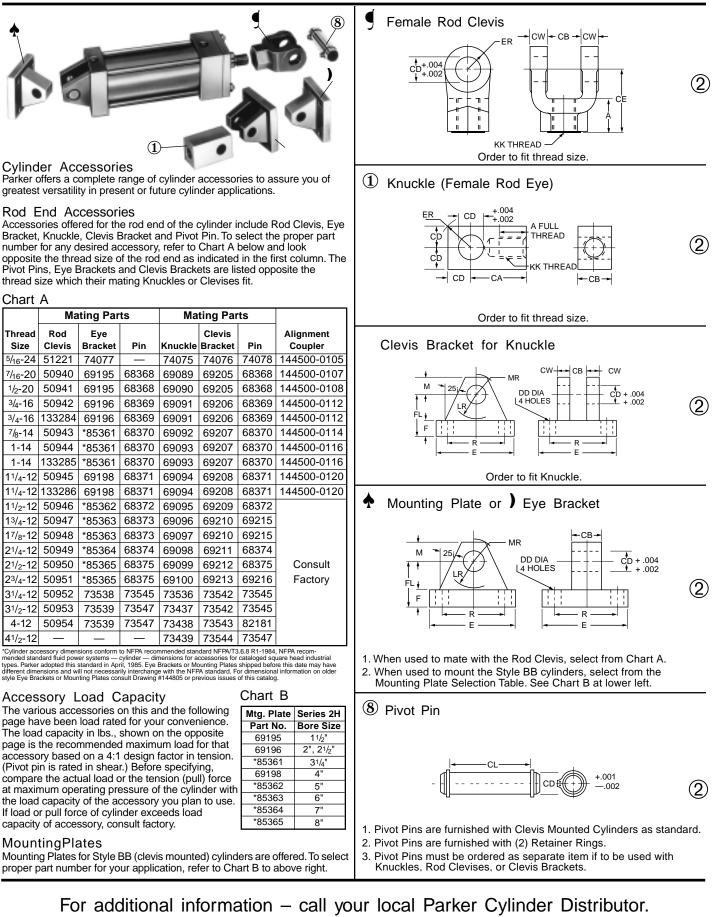
Place an "S" in the "special" position in the model number and specify "Low Friction Rod Gland."

*Registered Trademark of E.I. duPont de Nemours & Co. Inc.

For Cylinder Division Plant Locations - See Page II.



В



		Female Rod Clevis Part Number																	
	51221 [†]	50940	50941	50942	133284	50943	50944	133285	50945	133286	50946	50947	50948	50949	50950	50951	50952	50953	50954
А	¹³ /16	3/4	3/4	1 1/8	11/8	1 ⁵ /8	15⁄/8	15/8	2	2	21/4	3	3	31/2	3 1/2	31/2	31/2 ^{‡†}	4‡†	4‡†
СВ	11/ ₃₂	3/4	3/4	1 1/4	1 1⁄4	1 1/2	1 ¹ / ₂	1 1/2	2	2	21/2	21/2	21/2	3	3	3	4	4 ¹ / ₂	4 1/ ₂
CD	5/ ₁₆	1/ ₂	1/2	3/4	3/4	1	1	1	13⁄8	1 ³ /8	13⁄4	2	2	21/2	3	3	31/2	4	4
CE	21/4	1 1/2	1 1/2	21/8	2 ³ /8	2 ¹⁵ /16	2 ¹⁵ /16	31/8	33/4	41/8	41/2	5½	51/2	61/2	6 ³ /4	6 ³ /4	73/4	8 ¹³ /16	813/16
CW	13/ ₆₄	1/2	1/ ₂	5/8	5/8	3/4	3/4	3/4	1	1	1 ¹ /4	1 ¹ /4	1 1/4	1 1/2	11/2	1 ¹ / ₂	2	21/4	21/4
ER	19 _{/64}	1/2	1/ ₂	3/4	3/4	1	1	1	1 ³ /8	1 ³ /8	13⁄4	2	2	21/2	23/4	23/4	31/2	4	4
KK	^{15/} 16-24	⁷ /16-20	¹ / ₂ -20	³ ⁄4-16	³ ⁄4-16	7/8-14	1-14	1-14	1 ¹ /4-12	1 ¹ /4-12	1 ¹ /2-12	13⁄4-12	17/8-12	21⁄4-12	2 ¹ /2-12	23/4-12	3 ¹ /4-12	31/2-12	4-12
Load Capacity Lbs. O	2600	4250	4900	11200	11200	18800	19500	19500	33500	33500	45600	65600	65600	98200	98200	98200	156700	193200	221200

		Knuckle Part Number															
	74075	69089	69090	69091	69092	69093	69094	69095	69096	69097	69098	69099	69100	73536	73437	73438	73439
Α	3/4	3/4	3/4	1 1/8	1 1/8	15/8	2	21/4	2 ¹ /4	3	31/2	3 ¹ / ₂	35/8	4 [‡]	5	5 ¹ /2	5 ¹ /2
CA	11/ ₂	1 1/2	1 ¹ / ₂	2 ¹ /16	2 ³ /8	2 ¹³ /16	3 ⁷ /16	4	43/8	5	5 ¹³ /16	6 ¹ /8	6 ¹ / ₂	75/8	75/8	91/8	91 <u>/</u> 8
СВ	⁷ /16	3/4	3/4	1 1/4	1 ¹ / ₂	1 1/2	2	21/2	21/2	21/2	3	3	31/2	4	4	41/ ₂	5
CD	7/ ₁₆	1/2	1/ ₂	3/4	1	1	13/8	13⁄4	2	2	21/2	3	3	31/2	31/2	4	4
ER	19/ ₃₂	23/ ₃₂	23/ ₃₂	1 1/16	17/ ₁₆	1 ⁷ / ₁₆	1 ³¹ / ₃₂	21/2	2 ²⁷ / ₃₂	2 ²⁷ / ₃₂	3 %16	4 1/ ₄	41/4	4 ³¹ / ₃₂	4 31/32	5 ¹¹ /16	5 ¹¹ /16
КК	⁵ /16-24	⁷ /16-20	¹ / ₂ -20	³ ⁄4-16	⁷ /8-14	1-14	1 ¹ ⁄4-12	11/2-12	1 ³ /4-12	1 ⁷ /8-12	21/4-12	2 ¹ / ₂ -12	23⁄4-12	31/4-12	31/2-12	4-12	41/2-12
Load Capacity Lbs. O	3300	5000	5700	12100	13000	21700	33500	45000	53500	75000	98700	110000	123300	161300	217300	273800	308500

	Clevis Bracket for Knuckle Part Number												
	74076	69205	69206	69207	69208	69209	69210	69211	69212	69213	73542	73543	73544
СВ	15/ ₃₂	3/4	1 1⁄4	1 1/2	2	2 ¹ / ₂	2 ¹ / ₂	3	3	3 1/2	4	4 ¹ / ₂	5
CD	7/ ₁₆	1/2	3/4	1	1 ³ /8	13⁄4	2	2 ¹ / ₂	3	3	31/2	4	4
CW	3/8	1/2	5/ ₈	3/4	1	1 1/4	1 1/2	1 1/2	1 1/2	1 1/2	2	2	2
DD	17/ ₆₄	13/ ₃₂	17/ ₃₂	21/ ₃₂	21/ ₃₂	29/ ₃₂	1 1/ ₁₆	1 ³ /16	1 5/ ₁₆	1 5/16	1 ¹³ /16	2 ¹ /16	2 ¹ /16
E	21/4	31/2	5	6 ¹ / ₂	7 1/2	91/ ₂	12 3⁄4	12 ³ ⁄4	12 3/4	12 3⁄4	15 ¹ /2	17 1/2	17 1/2
F	3/8	1/2	5/8	3/4	7/8	7/8	1	1	1	1	1 ¹¹ / ₁₆	1 ¹⁵ /16	1 ¹⁵ / ₁₆
FL	1	1 1/2	17/8	2 ¹ /4	3	35/8	4 1/ ₄	4 ¹ / ₂	6	6	6 ¹¹ /16	7 ¹¹ /16	7 ¹¹ /16
LR	5/8	3/4	1 ³ ⁄16	1 1/2	2	23⁄4	3 ³ ⁄16	31/2	4 1/ ₄	4 1/ ₄	5	5 ³ /4	5 ³ /4
М	3/8	1/ ₂	3/4	1	1 ³ /8	13/4	2 ¹ / ₄	2 ¹ /2	3	3	31/2	4	4
MR	1/2	5/8	29/ ₃₂	1 1/4	1 ²¹ /32	27/ ₃₂	2 ²⁵ /32	31/8	3 19/ ₃₂	3 ¹⁹ / ₃₂	41/8	47/8	4 7/ ₈
R	1.75	2.55	3.82	4.95	5.73	7.50	9.40	9.40	9.40	9.40	12.00	13.75	13.75
Load Capacity Lbs. O	3600	7300	14000	19200	36900	34000	33000	34900	33800	36900	83500	102600	108400

	Eye Bracket and Mounting Plate Part Number												
	74077	69195	69196	85361*	69198	85362*	85363*	85364*	85365*	73538	73539		
СВ	⁵ /16	3/4	1 1⁄4	1 ¹ / ₂	2	21/2	21/2	3	3	4	41/2		
CD	5/ ₁₆	1/2	3/4	1	13/8	13/4	2	2 1/ ₂	3	3 1/2	4		
DD	17/ ₆₄	13/ ₃₂	17/ ₃₂	21/ ₃₂	21/ ₃₂	29/ ₃₂	1 1/16	1 ³ ⁄16	1 5/ ₁₆	1 ¹³ /16	2 ¹ / ₁₆		
E	21/4	2 ¹ / ₂	31/2	41/2	5	61/2	7 ¹ / ₂	81/2	91/ ₂	12 ⁵ /8	147/ ₈		
F	3/8	3/8	5/ ₈	7/8	7/8	1 1/8	1 ¹ /2	13⁄4	2	1 ¹¹ /16	1 ¹⁵ /16		
FL	1	1 1/8	17/8	23/8	3	3 ³ /8	4	43/4	5 ¹ /4	5 ¹¹ /16	6 ⁷ /16		
LR	5/8	3/4	1 1/4	11/2	2 1/8	21/4	21/2	3	31/4	4	41/2		
М	3/8	1/ ₂	3/4	1	1 ³ /8	13⁄4	2	2 ¹ / ₂	23/4	3 1/2	4		
MR	1/2	⁹ /16	7/ ₈	1 1/4	1 ⁵ /8	21/8	2 ⁷ /16	3	31/4	4 1/8	5 ¹ /4		
R	1.75	1.63	2.55	3.25	3.82	4.95	5.73	6.58	7.50	9.62	11.45		
Load Capacity Lbs. O	1700	4100	10500	20400	21200	49480	70000	94200	121900	57400	75000		

		Pivot Pin Part Number												
	74078	68368	68369	68370	68371	68372	68373	69215	68374	68375	69216	73545	82181	73547°
CD	7/ ₁₆	1/2	3/4	1	13/8	13⁄4	2	2	21/2	3	3	31/2	4	4
CL	1 5⁄16	17/8	25/8	31/8	41/8	5 ³ /16	5 ³ /16	5 ¹¹ /16	6 ³ /16	61/4	63⁄4	81/4	8 ⁵ /8	9
Shear Capacity Lbs. O	6600	8600	19300	34300	65000	105200	137400	137400	214700	309200	309200	420900	565800	565800

*Cylinder accessory dimensions conform to NFPA recommended standard NFPA/T3.6.8 R1-1984, NFPA recommended standard fluid power systems — cylinder — dimensions for accessories for cataloged square head industrial types. Parker adopted this standard in April, 1985. Eye Brackets or Mounting Plates shipped before this date may have different dimensions and will not necessarily interchange with the NFPA standard. For dimensional information on older style Eye Brackets or Mounting Plates consult Drawing #144805 or previous issues of this catalog. O See Accessory Load Capacity note on previous page.

•These sizes supplied with cotter pins.

†Includes Pivot Pin.

‡Consult appropriate cylinder rod end dimensions for compatibility.

For Cylinder Division Plant Locations - See Page II.



How to Order

Parker Series 2HX cylinders can be completely described by a model number consisting of coded symbols of digits and letters used in a prescribed sequence. To develop a model number, select only those symbols that represent the cylinder required, and place them in the sequence indicated by the example in Table A opposite. The example makes use of all places, although many model numbers will not require them all, as in the case where cushioning, double rod, or special modifications are not required. For additional cylinder specifications and dimensions see Parker Series 2H cylinder catalog.

When a Series 2HX actuator is ordered the following information must be developed.

1) The basic actuator model number including 2HX under Series as shown in Table A opposite.

2) If a rod extension is required, specify rod end thread Style 3.

3) A five digit code describing the valve and feedback type if any, and the supplier (Parker or customer).

4) If an actuator is to accept a D03, D05, D06, D07, or D08 pattern valve no additional information is necessary. If an actuator is to accept a servo valve or include any valve furnished by Parker, a manufacturer and model number should be supplied below the five digit code.

5) If a cylinder is to include a feedback device the following information must be called out below the five digit code:

Linear Displacement Transducer (LDT)

Analog Position

- 1) Position Output Signal and connection type (RB, RO)
- 2) Electrical Cable Length (from probe if integral cable)
- 3) Cable Length to AOM (if AOM specified)

Analog Position and Velocity

1) Position Output Signal

2) Velocity Output Signal and maximum piston velocity for calibration in inches per second

3) Electrical Cable Length to AOM

Digital Position

- 1) Specify Pulse Duration Output only (Specify Internal or External Interrogation and the number of circulations)
- 2) Data Ready Line
- Update Time

Linear Potentiometer (LRT)

- 1) Electrical connector position 1-4 cap end
- 2) Gross and net stroke if 1.75" rod dia. or smaller

Other Feedback Device

- 1) Device Type, Manufacturer, and Model Number
- 2) Output Signal

Integral Manifold Option

The integral manifold option is only available with the Parker Series 2HX 2" through 5" bores. All integral manifolds are available at the cap end position #1 only. For special integral manifolds for Parker Series 3LX and 3HX — consult factory.

Bolt-On Manifold Option

The bolt-on manifold option is available with Parker Series 2HX, 3LX and 3HX. Manifolds may be located on either the head or cap end at any position that does not interfere with mounting. For manifolds available by bore size, see the dimensions section of the catalog.

Feedback Option

Parker Series 2HX, 3LX, and 3HX actuators may be ordered prepared for a feedback device or prepared for and supplied with a feedback device. The Parker LRT option may only be ordered installed at the factory. See the ordering code on the opposite page. Parker's standard LDT option is a Temposonics[®] LH position sensor. To specify another manufacturer's magneto-restrictive position sensor place an "S" in the cylinder model code and specify the manufacturer's name and model number. Parker will install any other type and brand of feedback specified by the customer as long as it is reasonably designed to fit into an NFPA type cylinder — consult factory.

Failure or improper selection or improper use of the products and/or systems described herein or related items can cause death, personal injury and property damage.

This document and other information from Parker Hannifin Corporation, its subsidiaries and authorized distributors provide product and/or system options for further investigation by users having technical expertise. It is important that you analyze all aspects of your application, including consequences of any failure and review the information concerning the product or system in the current product catalog. Due to the variety of operating conditions and applications for these products or systems, the user, through its own analysis and testing, is solely responsible for making the final selection of products and systems and assuring that all performance, safety and warning requirements of the application are met.

The products described herein, including without limitation, product features, specifications, designs, availability and pricing, are subject to change by Parker Hannifin Corporation and its subsidiaries at any time without notice.

2HX Series Model Codes

The Parker 2HX Series model code is based on the standard Parker 2H Series model code system. The common modifications available for the Parker 2H are available with the Parker 2HX configuration as long as the modifications do not interfere with the Valve and Feedback options selected. The Bolt-On Manifold and Feedback options

described in this catalog and outlined below are available with the Parker 3L Series medium-duty hydraulic cylinder and with the Parker 3H Series (7" and 8" bore) heavy-duty hydraulic cylinder. Specify "3LX" and "3HX" respectively in the model code described below. Integral manifolds are not available as standard for the 3LX and 3HX.

Bore Size	Cushion Head End	Double Rod	Mounting Style	Mounting Modifi- cation	Series	Piston	Ports	Common Modifi- cations	Special Modifi- cations	Piston Rod Number	Rod End Thread Style	Thread Type	Cushion Cap End	Stroke
4.00	С	-	TC	Р	2HX	L	Т	V*	S	1	4	А	—	X24.00
Specify. Consult dimension tables for available bore sizes. Also see Parker Series 2H.	Specify only if cushion Head End is required.	Consult factory for double rod cylinders.	Specify Mounting Style. Consult dimension tables for available mounting styles. Also see Parker Series 2H.	Specify P- for thrust key mounting. *ONLY IF RE- QUIRED.	Specify Series 2HX for 2"-6" bores, 3HX for 7" and 8" bores, 3LX for medium- duty 2" - 6" bores.	Use L for Lipseal Piston. Use K for Hi-Load Piston. Use C for ring type piston.	Specify "T" for SAE straight thread ports. (all manifolds) Optional ports available without manifolds (see 2H).		Specify an "S" for all special modifications not called out in the five digit code below.	Specify rod code number. Consult dimension tables for available rod diameters and section C, page 96 for rod buckling consider- ations.	Specify Style 4, Small Male. Style 8, Intermediate Male. Style 3, Special. Specify KK, A, LA or W dimension required.		Cap End Cushions are not avilable with LDT or LRT feedback. Specify C for cap cushion with no feedback.	Specify in inches. Show symbol "x" just ahead of stroke length.

Table A — Basic Model Numbers

Table B — Valve and Feedback Codes (Required for 2HX Ordering)

Valve Manifold	Valve Pattern Group	Valve Location	Feedback Option	Feedback Furnished	Feedback Protective Enclosures
N = None	N = Not applicable	N = Not Applicable	N = None	N = Not Applicable	N = Not Applicable
B = Bolt-On*	A = Servo Group A††	H = Head	C = LDT•	1 = Prepare to accept	A = False Stage
I = Integral**	D = Servo Group D††	C = Cap	F = LRT••	2 = Included	D = Light Duty
	G = D03 (Group G)		X = Other***		F = Medium Duty
	H = D05 (Group H)		(Please specify)***		
	J = D06 (Group J)†				
	K = D07 (Group K)†		B = BALLUFF		
	M = D08 (Group M)†				
	X = Other***				
	(Please Specify)***				

* Bolt-On Manifolds will be located at position #1 unless an "S" is placed in the cylinder model code and the mounting position is indicated. Bolt-On Manifolds may be positioned on either the head or cap end at any location not occupied by a mount or port or cushion. ** Integral Manifolds are only available at cap end position #1.

*** When selecting "other" an "S" must be placed in the model code and the valve or feedback device must be specified by the customer.

† Valve patterns D06 (Group J), D07 (Group K), and D08 (Group M) are only available as Bolt-On Manifolds. Consult factory for DD Mounts.

tt See Valve group table on page 154 & 172 for Servo Valve mounting pattern descriptions.

• When an LDT is to be supplied by the customer, Parker prepares the actuator with an SAE port, magnet, and gun drilled to accept a 2.5" dead zone LDT.

•• LRTs can only be installed by Parker at the factory. Electrical connector will be at position #4 standard.

Example 1: Actuator with LDT feedback only (2.5" dead band LDT), and 0 to 10 VDC grounded output with 15 foot electrical cable.

2.50" C-2HXT 34 × 12.000" NNNC2N 1) 0 to 10 VDC

2) 15 foot electrical cord

Example 2: Actuator to accept a BD-30 servo valve and to **include** analog LDT with velocity output, 15 ips max velocity, low friction seals and extra-heavy-duty enclosure. Cushioned head end.

6.0 CC 2HX TS 14 A X 60 BDCC2A Low friction piston and rod seals Velocity calibration: +10 VDC = 15 ips extending



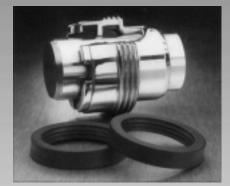
Parker TS-2000 seal designed to eliminate cylinder rod seal leakage.

Parker Series 2H Heavy Duty and Series 3L Medium Duty Hydraulic Cylinders with the TS-2000 seal offers positive protection against cylinder rod leakage under the most demanding applications.

The TS-2000 seal is the product of countless hours of research, development and extensive field testing and is only available on Parker Cylinders.

Based on the popular Parker Serrated Lipseal rod design, the TS-2000 incorporates the pressurecompensated, uni-directional characteristics of a U-cup with the multiple edge sealing effectiveness of compression-type stacked-packings.

The goal for the Parker team was to design a rod seal suitable for all types of applications, regardless of pressure profile. It had to be composed of a



"Jewel" gland with wiperseal and TS-2000 cylinder rod seal.

material that would not react chemically with hydraulic fluids. And it had to produce better and more reliable "dry rod" performance than the standard serrated lip-seal design in a broad range of applications.

The result is the TS-2000 seal, designed especially to eliminate rod seal leakage in the most demanding applications. It features a special polyurethane material that will not react chemically with petroleum-based hydraulic •uid, is extremely resistant to abrasion and extrusion, and provides exceptional service life. It has more sealing edges than other seals on the market, which in turn produces "dry rod" performance. The seal geometry was refined for maximum stability in the groove and has excellent performance characteristics throughout a broad range of pressures and piston rod velocities.

The Parker design team was successful!

TS-2000 rod seal has not failed in any of the test applications in the lab or on the job, no matter how tough or demanding.

For more information on the TS-2000 call or write your local Parker distributor or Parker Hannifin Corporation, Cylinder Division, 500 S. Wolf Road, Des Plaines, IL 60016, 847-298-2400.

> Worldclass Quality Products and Service

